

Confidential

Realtime Feedback Tool for Nasal Surgery

— Felix Jonathan, Michael Norris —
Mentors - Narges Ahmidi, Dr.
Masaru Ishii, Dr. Lisa Ishii

Background

Septoplasty surgery is a surgery that uses a surgeon's instinct in estimating nasal region to cut.

Training residents in septoplasty is hard because the residents cannot see the septoplasty process demonstration that's being done by the fellow

There is no existing technology that is being used for visualizing the septum surface and visualizing nasal cutting tool line-of-cut for septoplasty surgery.

Goal

Fully functional and clinically acceptable software that assists surgeons in performing septoplasty, and increases the accuracy of the procedure.

Informative visualization that improve the learning environment for the attending septoplasty surgery resident.

Technical Summary

Determine surgical scissor line-of-cut from training with phantom

Generate septum surface using EM pointer

Generate line-of-cut for surgical scissors using EM tracker

Visualize the predicted line-of-cut to the surgeon in real-time

Deliverables

Requirement: All Code in C++ / Python

Minimum:

1. Training procedure for any model of scissors
 - a. Meet surgical team biweekly and iterate on design until completed
2. Line of Cut prediction
3. Visualizing line of cut prediction and septum surface / phantom
4. Septum surface reconstruction by tracing the actual septum
5. Documentation for all software and mechanical designs

Deliverables

Expected:

1. Real-time visualization of line of cut prediction on septum surface (> 15 Hz refresh rate)
2. Http-based web service to send data from existing software to our project
3. Software that validates the accuracy of a cut with respect to the prediction on the phantom

Maximum:

1. Get maximum accuracy for line-of-cut prediction using existing sensor (to be updated when we get complete specification of every sensor and tracker we use).
2. Septum surface reconstruction by randomized septum surface touching.

Dependencies

1. EM Trackers and EM Control Unit -- provided by mentor
2. EM Tracker holder -- provided by mentor, expected arrival in March
 - a. We will rapid-prototype a temporary EM tracker holder for testing purposes.
3. Surgical Scissors -- provided by mentor
4. Access to laboratory environment -- provided by mentor
5. Learning CISST library for a variety of applications (pivot calibration, 2D-3D registration, etc.)

Dependencies

6. Code for Communicating with EM Tracker and reading pose in realtime -- provided by mentor
7. Pointer tool for surface reconstruction -- provided by mentor
8. Phantom for septal plane -- use chicken breast

Management Plan - Meetings

Felix and Michael meet every Tuesday from 5-10pm, Friday from 3-8pm

Felix and Michael working on Saturday from 9am-7pm

Biweekly meetings with surgical team

Biweekly meetings with mentor to give progress updates

Management Plan - Skills

Felix -- Computer Vision, Robotics, CAD design, machine shop skills, software development in C++ and Python

Michael -- Development of Visualization / analysis software, high performance computing, backend web infrastructure, software engineering

Management Plan - Bookkeeping

Confidential

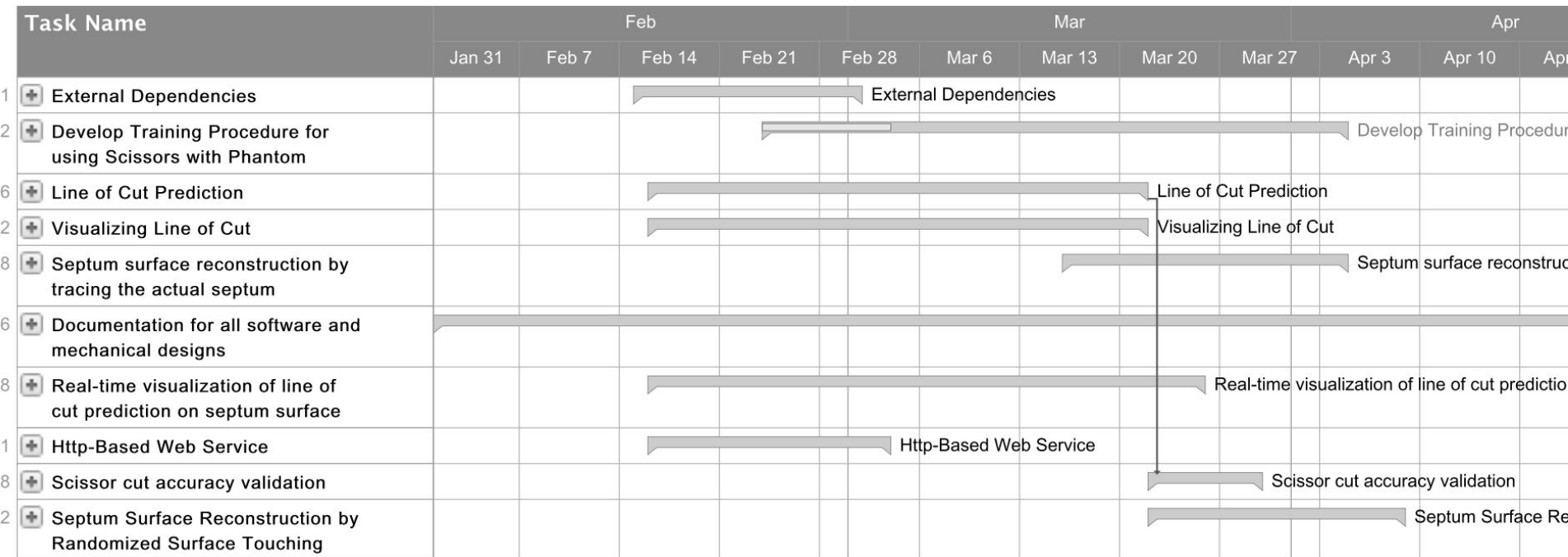
Code backed up in private Github repository

Use Jira to track task completion

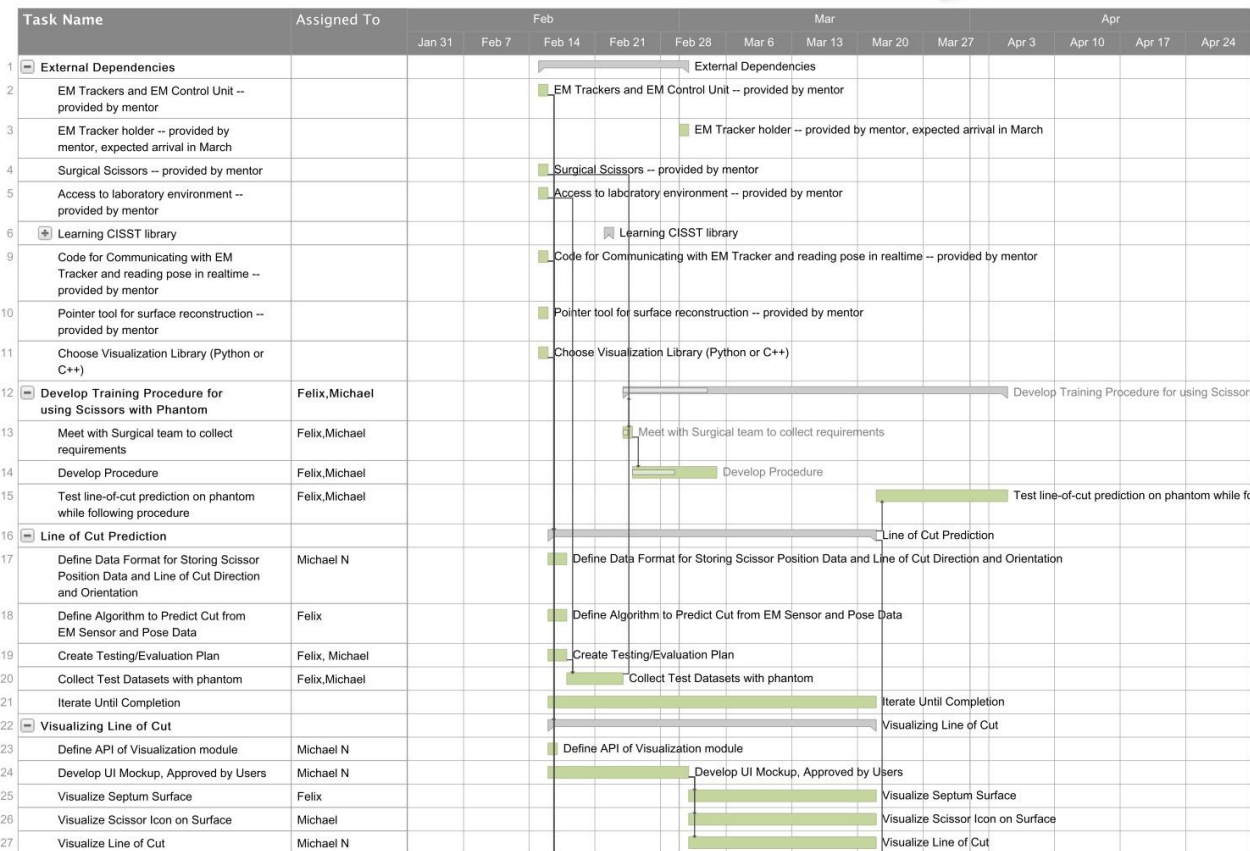
Inventor's notebook kept in accordance with best practices (for patent purposes)

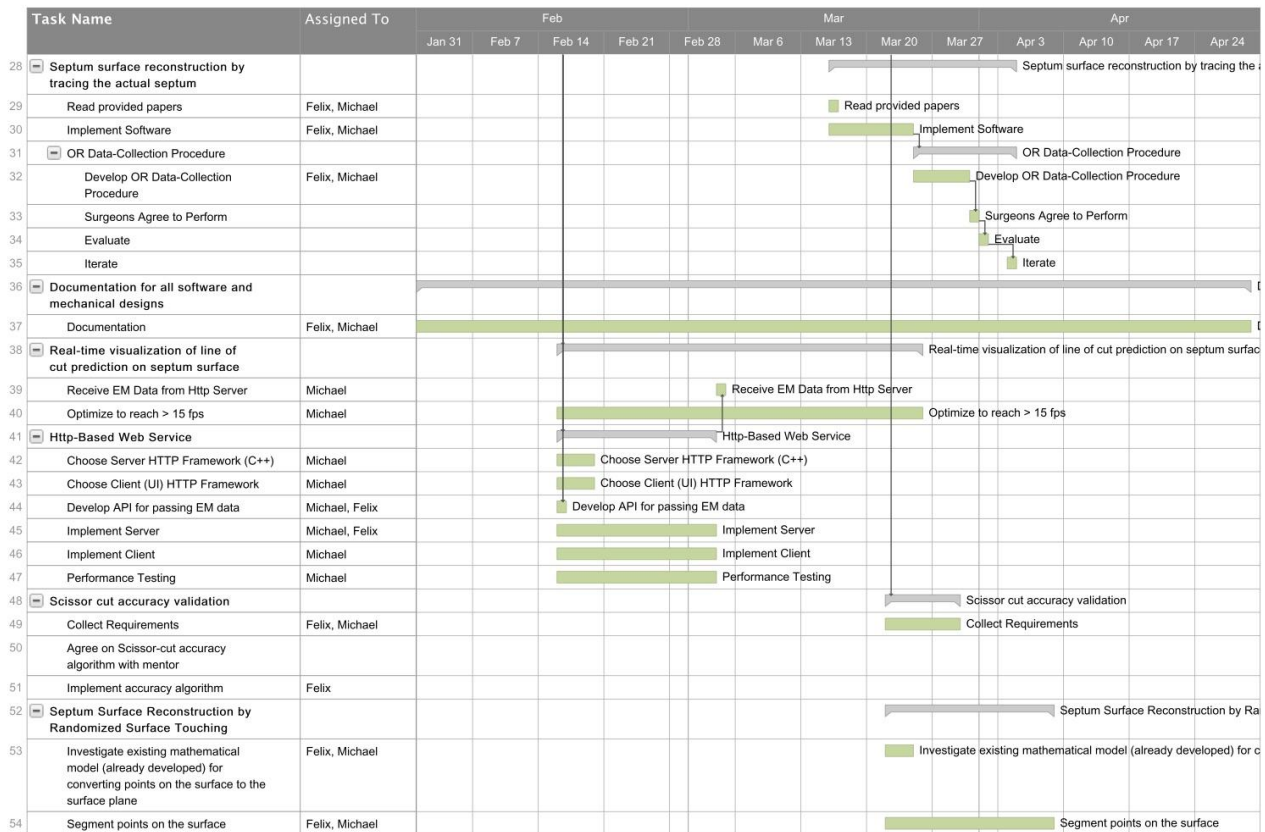
Management Plan - Gantt Chart

Confidential



Line of Cut Prediction





Management Plan - Gantt Chart

Confidential

https://app.smartsheet.com/b/home?lx=v3Shk9EJhm_KCqJtsqN58w

Purchase Requests

Jira subscription (\$10/month) for tracking tasks, subtasks, and development progress

Private Github repository (\$7/month) to backup code

Chickens for phantom (market price)



Confidential