# Realtime Feedback Tool for Nasal Surgery

Felix Jonathan, Michael Norris Mentors - Narges Ahmidi, Dr. Masaru Ishii, Dr. Lisa Ishii

### Background

Septoplasty surgery is a surgery that uses a surgeon's instinct in estimating nasal region to cut.

Training residents in septoplasty is hard because the residents cannot see the septoplasty process demonstration that's being done by the fellow

There is no existing technology that is being used for visualizing the septum surface and visualizing nasal cutting tool line-of-cut for septoplasty surgery.

#### Goal

Fully functional and clinically acceptable software that assists surgeons in performing septoplasty, and increases the accuracy of the procedure.

Informative visualization that improve the learning environment for the attending septoplasty surgery resident.

#### **Technical Summary**

Determine surgical scissor line-of-cut from training with phantom

Generate septum surface using EM pointer

Generate line-of-cut for surgical scissors using EM tracker

Visualize the predicted line-of-cut to the surgeon in real-time

#### **Deliverables**

#### **Requirement: All Code in C++ / Python**

#### Minimum:

- 1. Training procedure for any model of scissors
  - a. Meet surgical team biweekly and iterate on design until completed
- 2. Line of Cut prediction
- 3. Visualizing line of cut prediction and septum surface / phantom
- 4. Septum surface reconstruction by tracing the actual septum
- 5. Documentation for all software and mechanical designs

#### **Deliverables**

#### **Expected:**

- 1. Real-time visualization of line of cut prediction on septum surface (> 15 Hz refresh rate)
- 2. Http-based web service to send data from existing software to our project
- 3. Software that validates the accuracy of a cut with respect to the prediction on the phantom

#### Maximum:

- 1. Get maximum accuracy for line-of-cut prediction using existing sensor (to be updated when we get complete specification of every sensor and tracker we use).
- 2. Septum surface reconstruction by randomized septum surface touching.

#### **Dependencies**

- 1. EM Trackers and EM Control Unit -- provided by mentor
- 2. EM Tracker holder -- provided by mentor, expected arrival in March
  - a. We will rapid-prototype a temporary EM tracker holder for testing purposes.
- 3. Surgical Scissors -- provided by mentor
- 4. Access to laboratory environment -- provided by mentor
- Learning CISST library for a variety of applications (pivot calibration, 2D-3D registration, etc.)

#### **Dependencies**

- 6. Code for Communicating with EM Tracker and reading pose in realtime -- provided by mentor
- 7. Pointer tool for surface reconstruction -- provided by mentor
- 8. Phantom for septal plane -- use chicken breast

## **Management Plan - Meetings**

Felix and Michael meet every Tuesday from 5-10pm, Friday from 3-8pm

Felix and Michael working on Saturday from 9am-7pm

Biweekly meetings with surgical team

Biweekly meetings with mentor to give progress updates

#### **Management Plan - Skills**

Felix -- Computer Vision, Robotics, CAD design, machine shop skills, software development in C++ and Python

Michael -- Development of Visualization / analysis software, high performance computing, backend web infrastructure, software engineering

# Management Plan - Bookkeeping Confidential

Code backed up in private Github repository

Use Jira to track task completion

Inventor's notebook kept in accordance with best practices (for patent purposes)

# **Management Plan - Gantt Chart**

	Task Name		Feb					Mar		Apr				
		Jan 31	Feb 7	Feb 14	Feb 21	Feb 28	Mar 6	Mar 13	Mar 20	Mar 27	Apr 3	Apr 10	Арі	
1	衝 External Dependencies				A	Exter	nal Depende	ncies						
12	Develop Training Procedure for using Scissors with Phantom										Develop	o Training Pr	ocedur	
16	Line of Cut Prediction								Line of	Cut Prediction	on			
22	Visualizing Line of Cut				· · · · · · · · · · · · · · · · · · ·				Visualiz	zing Line of (	Cut			
28	Septum surface reconstruction by tracing the actual septum										Septum	surface reco	onstruc	
36	Documentation for all software and mechanical designs													
38	Real-time visualization of line of cut prediction on septum surface									Real-time vi	sualization of	line of cut pr	edictio	
41	Http-Based Web Service					Ht	ttp-Based We	eb Service						
48	Scissor cut accuracy validation									Sciss	or cut accura	cy validation		
52	Septum Surface Reconstruction by Randomized Surface Touching											Septum Surfa	ace Re	

#### Line of Cut Prediction



1	Task Name	Assigned To		Feb				Mar				Ap	r	
6	External Dependencies					Exter	nal Depender	ncies						
	EM Trackers and EM Control Unit provided by mentor			EM Tra	ackers and E	M Control Un	it provided	by mentor						
	EM Tracker holder provided by mentor, expected arrival in March					EM T	racker holder	provided	by mentor, e	xpected arr	val in March			
F	Surgical Scissors provided by mentor			Surgica	al Scissors -	- provided by	mentor							
5	Access to laboratory environment provided by mentor			Access	to laborato	ry environmer	t provided	by mentor						
5	Learning CISST library				📃 Learni	ing CISST libr	ary							
	Code for Communicating with EM Tracker and reading pose in realtime provided by mentor			Code f	or Communi	icating with EM	1 Tracker and	d reading pos	se in realtime	e provide	l by mentor			
	Pointer tool for surface reconstruction provided by mentor			Pointer	tool for surf	face reconstru	ction provi	ded by mente	or					
	Choose Visualization Library (Python or C++)			Choose	e Visualizati	on Library (Py	thon or C++)							
2	<ul> <li>Develop Training Procedure for using Scissors with Phantom</li> </ul>	Felix,Michael			-						Develo	p Training Pr	rocedure for u	sing Sciss
3	Meet with Surgical team to collect requirements	Felix,Michael			<b>6</b> ]_Me	eet with Surgio	al team to co	llect requirer	ments					
1	Develop Procedure	Felix,Michael					Develop Proc	edure						
5	Test line-of-cut prediction on phantom while following procedure	Felix,Michael							1		Test lin	e-of-cut prec	liction on pha	ntom while
6	Line of Cut Prediction								Line of	Cut Predict	ion			
7	Define Data Format for Storing Scissor Position Data and Line of Cut Direction and Orientation	Michael N		Del	fine Data Fo	rmat for Storir	g Scissor Po	sition Data a	ind Line of C	ut Directior	and Orientati	on		
3	Define Algorithm to Predict Cut from EM Sensor and Pose Data	Felix		Def	fine Algorithr	m to Predict C	ut from EM S	ensor and P	ose Data					
	Create Testing/Evaluation Plan	Felix, Michael		Cre	ate Testing/	Evaluation Pla	an							
	Collect Test Datasets with phantom	Felix,Michael			Colle	ect Test Datas	ets with phar	ntom						
1	Iterate Until Completion				da.				Iterate	Until Comp	etion			
2	Visualizing Line of Cut								Visuali:	ing Line of	Cut			
3	Define API of Visualization module	Michael N		Defin	e API of Vis	ualization mo	tule							
-	Develop UI Mockup, Approved by Users	Michael N				Deve	op UI Mocku	p, Approved	by Users					
5	Visualize Septum Surface	Felix							Visuali:	e Septum	Surface			
	Visualize Scissor Icon on Surface	Michael					1		Visualiz	e Scissor I	con on Surfac	e		
F	Visualize Line of Cut	Michael N							Visuali	e Line of C	ut			

sk Name	Assigned To									Apr			
<ul> <li>Septum surface reconstruction by tracing the actual septum</li> </ul>										Septu	m surface re	construction by	tracing the
Read provided papers	Felix, Michael						📕 Rea	d provided p	papers				
Implement Software	Felix, Michael						0	_lr	nplement	Software			
OR Data-Collection Procedure								- p		OR D	ata-Collection	n Procedure	
Develop OR Data-Collection Procedure	Felix, Michael									Develop OR Da	ata-Collection	Procedure	
Surgeons Agree to Perform									1	_Surgeons Ag	ree to Perfor	m	
Evaluate										Evaluate			
Iterate										lterate	i i		
<ul> <li>Documentation for all software and mechanical designs</li> </ul>													
Documentation	Felix, Michael					1							
<ul> <li>Real-time visualization of line of cut prediction on septum surface</li> </ul>									Real-time	e visualization o	of line of cut p	prediction on se	ptum surfac
Receive EM Data from Http Server	Michael					Receive EM I	Data from Htt	p Server					
Optimize to reach > 15 fps	Michael		1						Optimize	to reach > 15 f	ps		
Http-Based Web Service					Н	ttp-Based We	b Service						
Choose Server HTTP Framework (C++)	Michael			Choose Serv	er HTTP Fra	mework (C++	)						
Choose Client (UI) HTTP Framework	Michael			Choose Clier	nt (UI) HTTP	Framework							
Develop API for passing EM data	Michael, Felix		Deve	lop API for pa	assing EM da	ata							
Implement Server	Michael, Felix			1.	In	nplement Ser	ver						
Implement Client	Michael		8			nplement Clie	nt						
Performance Testing	Michael				P	erformance T	esting						
Scissor cut accuracy validation								1	S	cissor cut accu	acy validatio	n	
Collect Requirements	Felix, Michael							f.	C	ollect Requirem	ients		
Agree on Scissor-cut accuracy algorithm with mentor													
Implement accuracy algorithm	Felix												
Septum Surface Reconstruction by Randomized Surface Touching									1		Septum Su	rface Reconstru	ction by Ra
Investigate existing mathematical model (already developed) for converting points on the surface to the surface plane	Felix, Michael							li li	nvestigate	existing mathe	matical mod	el (already deve	eloped) for c
Segment points on the surface	Felix, Michael										Segment po	pints on the sur	ace

# Management Plan - Gantt Chart

https://app.smartsheet.com/b/home?lx=v3Shk9EJhm\_KCqJtsqN58w

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### **Purchase Requests**

Jira subscription (\$10/month) for tracking tasks, subtasks, and development progress

Private Github repository (\$7/month) to backup code

Chickens for phantom (market price)