

Group 21: Robotic Soft Tissue Assessment

Plan Presentation

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The Goal

The goal of this project to design and conduct a study that quantifiably assess robotically-assisted soft tissue manipulation.

The further aim of this project is to develop an algorithm to create otolaryngology-specific virtual fixtures to improve robotically-assisted surgical accuracy.

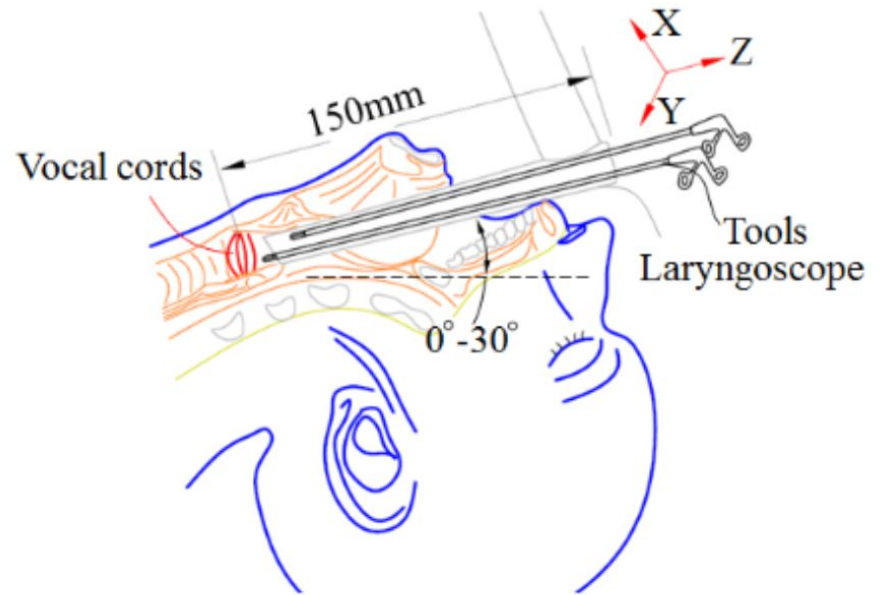


Figure 1: Microlaryngeal Phonosurgery

Building Vocal Cord Phantom

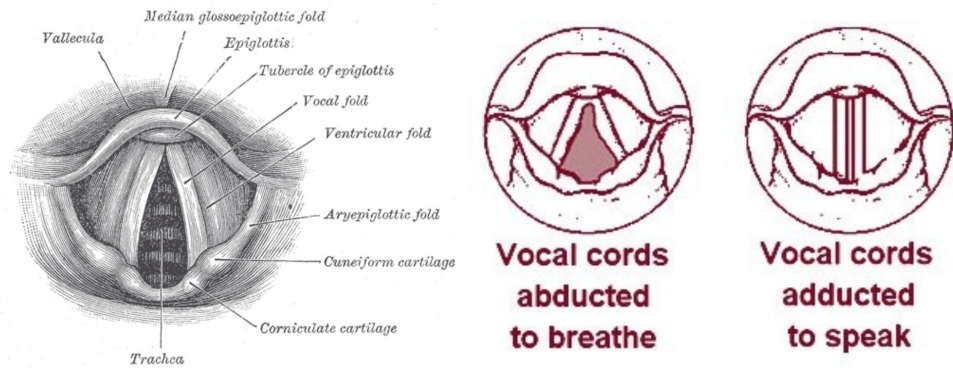
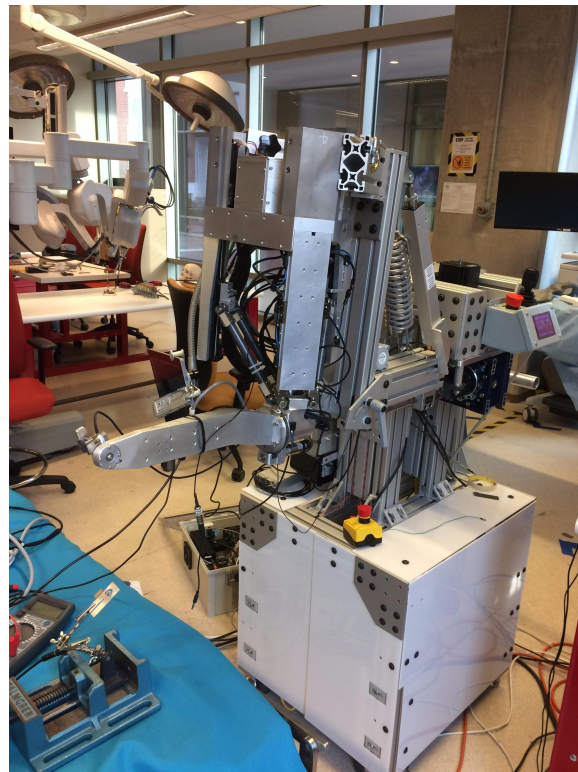
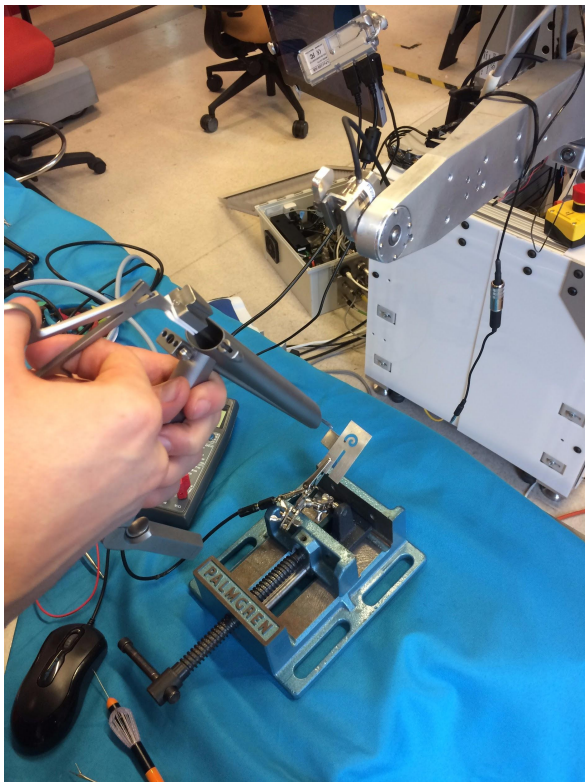


Figure 2: Anatomy of the glottis
(Image credit Gray's Anatomy of the Human Body, 20th Edition)



Figure 3: Vocal cord animation

Galen Robot in Mock OR



Removal of Cyst



Figure 4: SerpENT surgical instrument.
(Image Credit: <http://www.entriguesurgical.com/>)

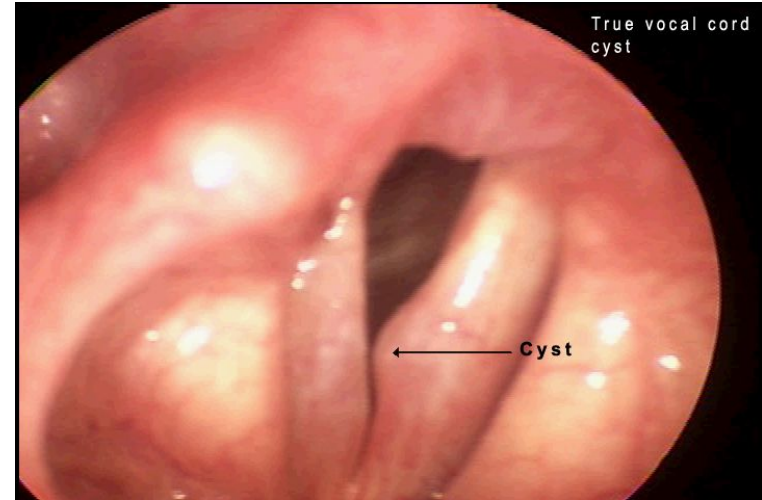


Figure 5: Vocal Cord Cyst

Assessment Software

1. Measure Proper Cutting from Video Recording

→ draw an ideal trajectory and calculating deviation using MATLAB

2. Calculate Benign Tissue (White) to Cyst (Red) Ratio of Removed Region

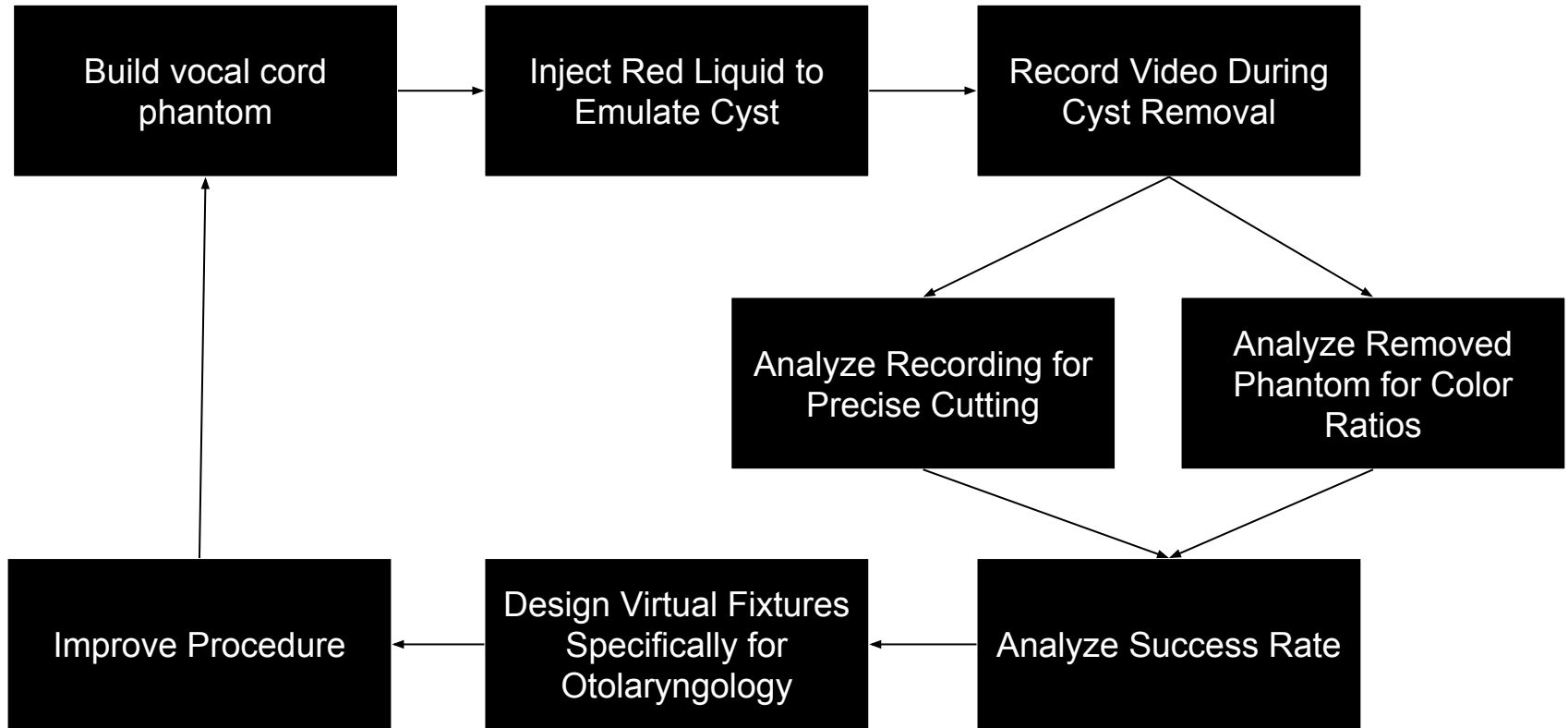
→ low $\text{WhiteArea}/\text{RedArea}$ ratio in the removed piece

→ minimum RedArea value corresponding to the size of the cyst.



Figure 6: Galen microlaryngeal phonosurgery cadaver setup.

Overall Technical Approach



List of Deliverables

Minimum

- I. Study design for surgery, data collection and analysis
- II. CAD design of a phantom to conduct surgical experiments on
- III. Collected data and results of surgical experiments on 3D printed phantom conducted by experts & med students with and without robotic assistance
- IV. Computer vision based analysis algorithm using Matlab/Python to quantify success of vocal cyst removal surgery

Expected

- I. Study design for conducting surgery on an non-living animal vocal cord
- II. Collected data and results of surgical experiments on animal vocal cord conducted by experts & med students with and without robotic assistance
- III. Improved computer vision based analysis algorithm to quantify success of vocal cyst removal surgery

Maximum

- I. 3D virtual fixture algorithm developed for the robot using C++
- II. Study design for conducting robotically-assisted surgery with virtual fixtures
- III. Collected data and results of robotically-assisted surgical experiments with virtual fixtures on the phantom conducted by experts
- IV. Comparison of quantified success results of non-assisted, robotically-assisted with no virtual fixtures, and robotically-assisted with virtual fixtures surgeries on the phantom



Key Dates & Assigned Responsibilities

	Feb W4	Mar W1	Mar W2	Mar W3	Mar W4	Mar W5	Apr W1	Apr W2	Apr W3	Apr W4	May W1	May W2	
Minimum													
Plan Presentation	Red												
Design phantom experiment procedure	Light Blue												
Design phantom CAD		Light Blue											
Manufacture phantoms			Light Blue										
Conduct surgery with experts				Light Blue									
Conduct surgery with med students					Light Blue								
Develop quantitative analysis algorithm						Light Blue							
Analyze experiment results							Light Blue						
Expected								Dark Grey	Dark Grey	Dark Grey	Dark Grey	Dark Grey	
Project Checkpoint Presentation							Red						
Design animal experiment procedure							Light Blue						
Conduct surgery with experts								Light Blue					
Improve quantitative analysis algorithm									Light Blue				
Analyze experiment results										Light Blue			
Maximum										Dark Grey	Dark Grey	Dark Grey	
Design VF experiment procedure										Light Blue			
Develop VF algorithm											Light Blue		
Conduct surgery with experts												Light Blue	
Compare results with past experiments													Light Blue
Prepare Poster													Light Blue
Project Final Presentation													Red



List of Dependencies & Plan for Resolving

Dependency	Resolution
Computer Vision library decision and tutorial	Meet with Paul Wilkening
3D CAD software decision and tutorial	Meet with Yunuscan Sevimli
Mock OR access	Access granted
3D printer access for phantom manufacturing	Access granted
Get experts to conduct experiment Mar W4	Confirmation received
Get experts to conduct experiment Apr W2	Meet with Yunuscan Sevimli
Get experts to conduct experiment May W1	Meet with Yunuscan Sevimli
Get med students to conduct experiment Mar W4	Confirmation received
Get permission to experiment with animals	Meet with Yunuscan Sevimli
ROS background for virtual fixture algorithm	Meet with Paul Wilkening

Last Minute Update: Still need to submit IRB forms, and decide on the budget for building the phantom. Scheduled meeting with Dr. Akst and Dr. Razavi.



References

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Stanković P, Vasić M, Djukić V, Janosević Lj, Vukasinović M. Vocal fold masses removal--the sub epithelial micro flap technique. *Acta Chir Iugosl*. 2008;55(4):43-7.

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