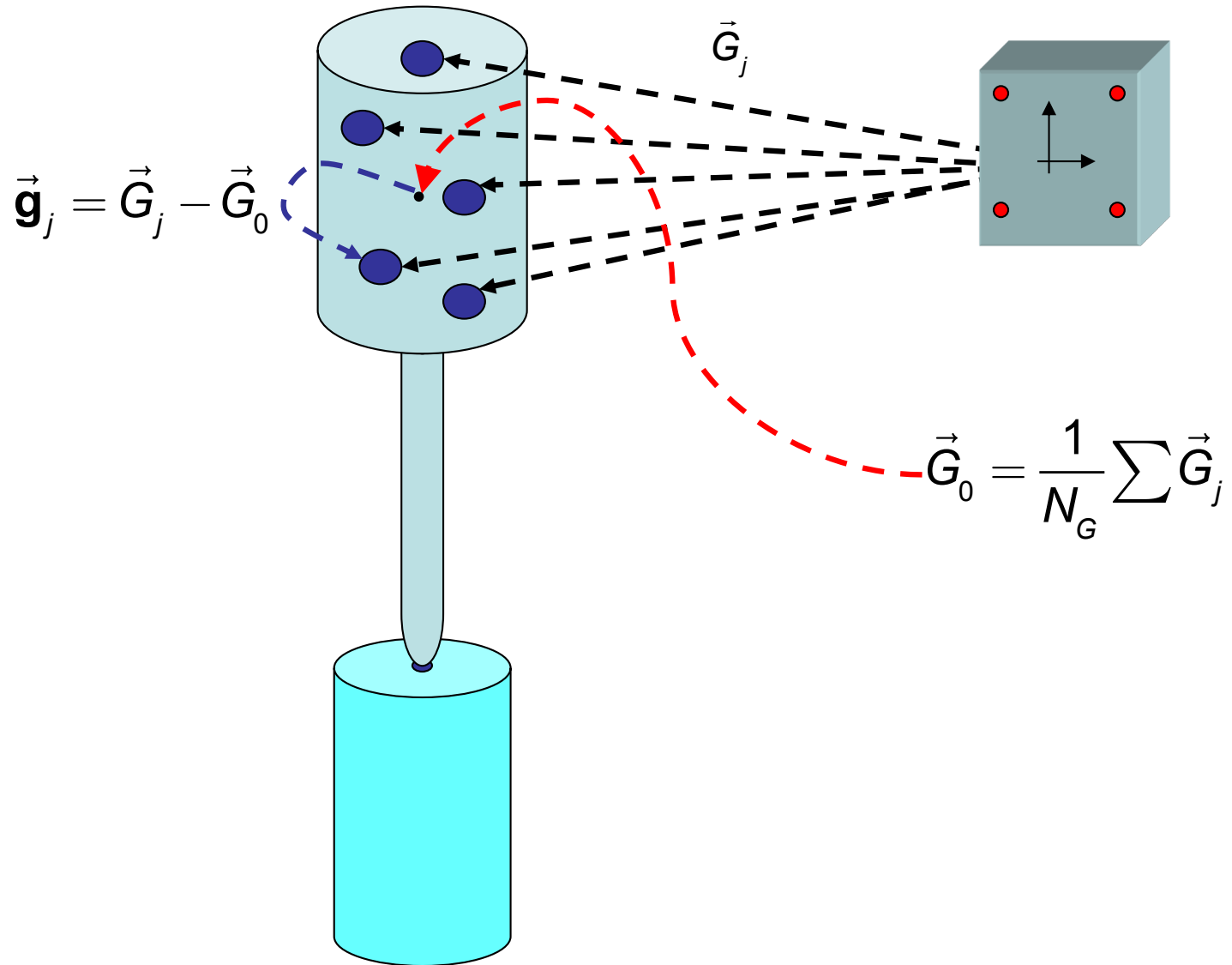


Defining the EM rigid body



Calibrating the EM Pointer (pivot calibration)

