



## Enhancement of US-CT registration accuracy for spinal surgery

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Mentor: Muyinatu Bell

Background presentation – Advanced Computer-Integrated Surgery (601.656)

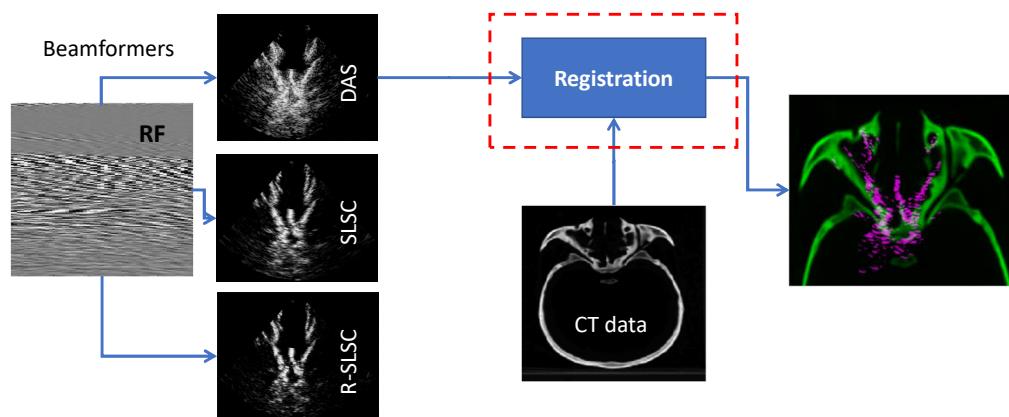
Spring 2018

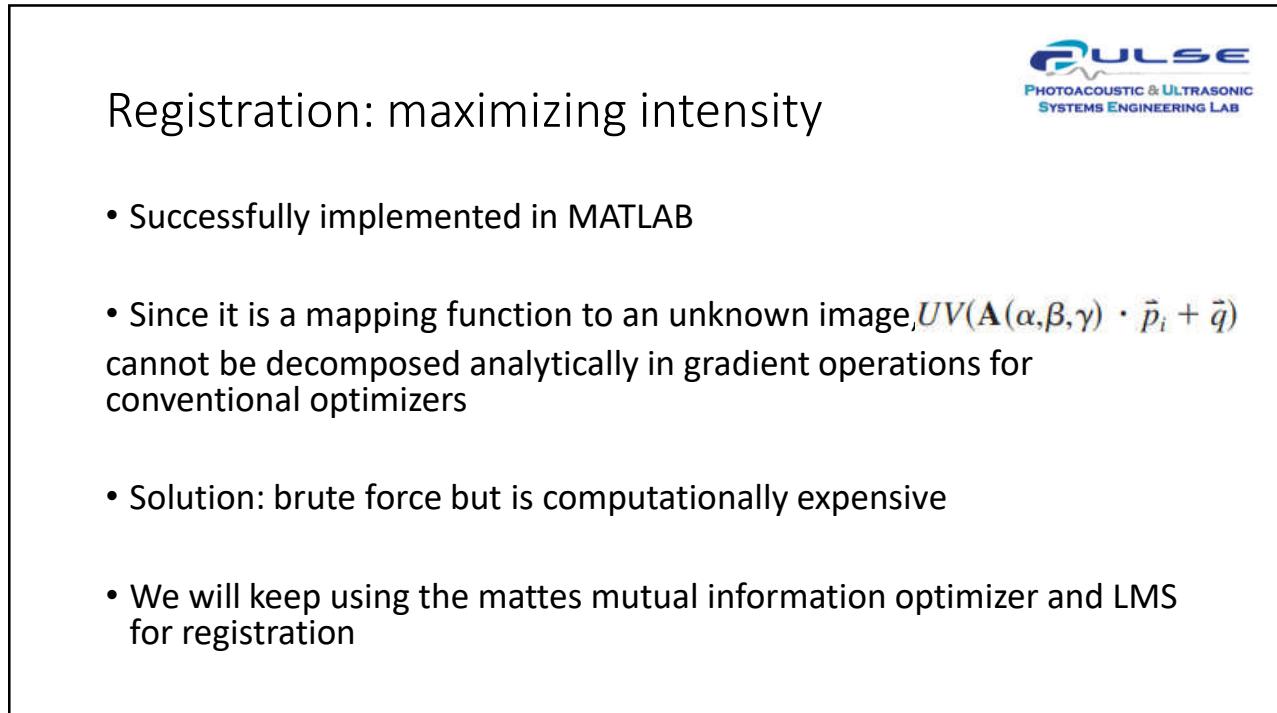
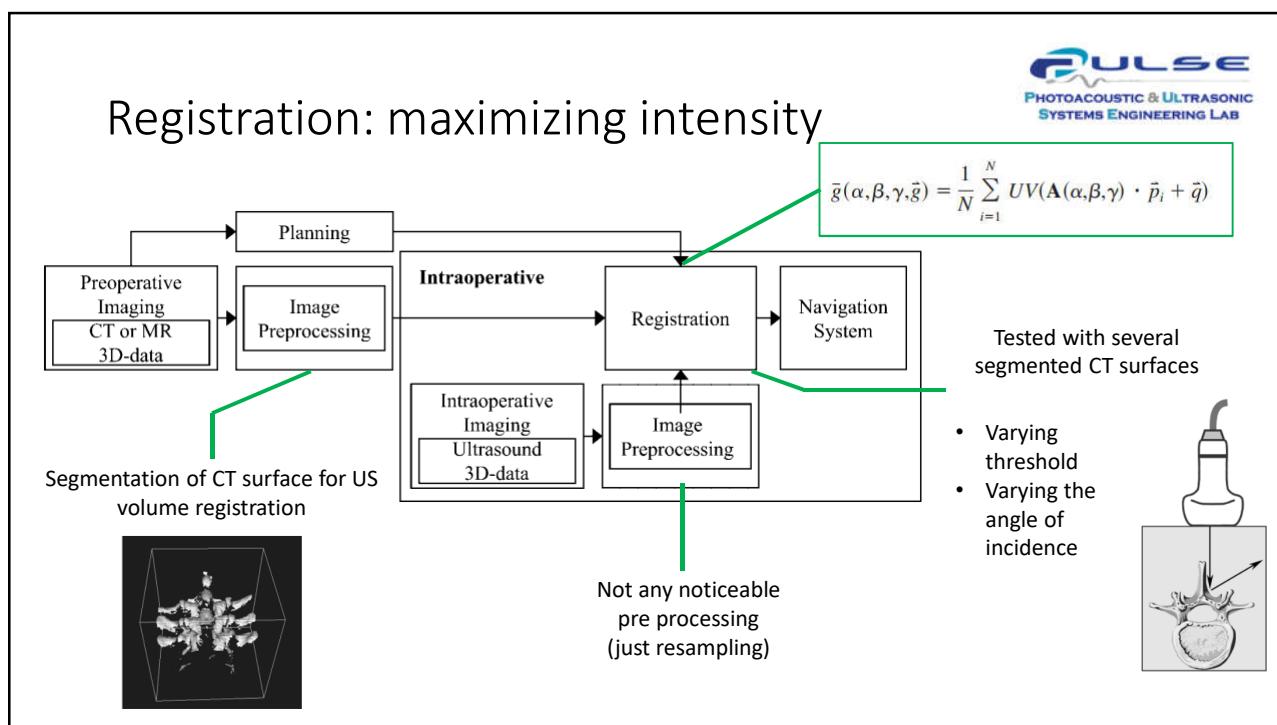
## Summary of the project

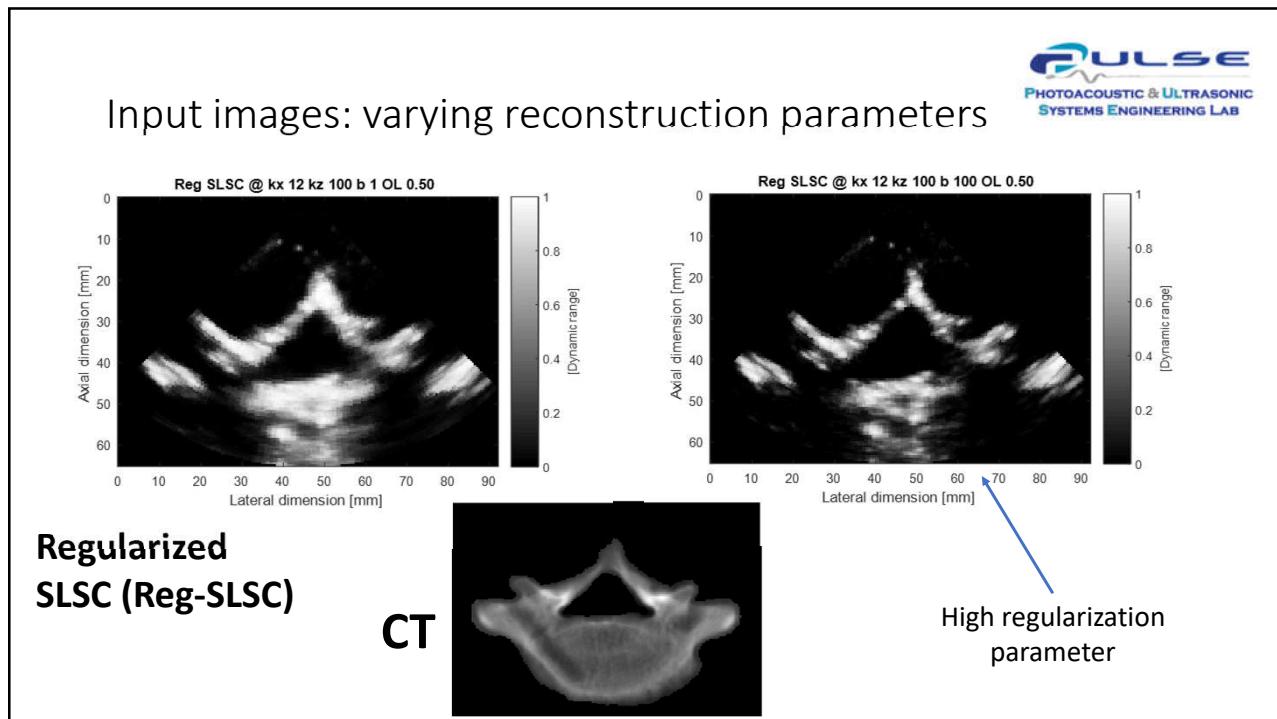
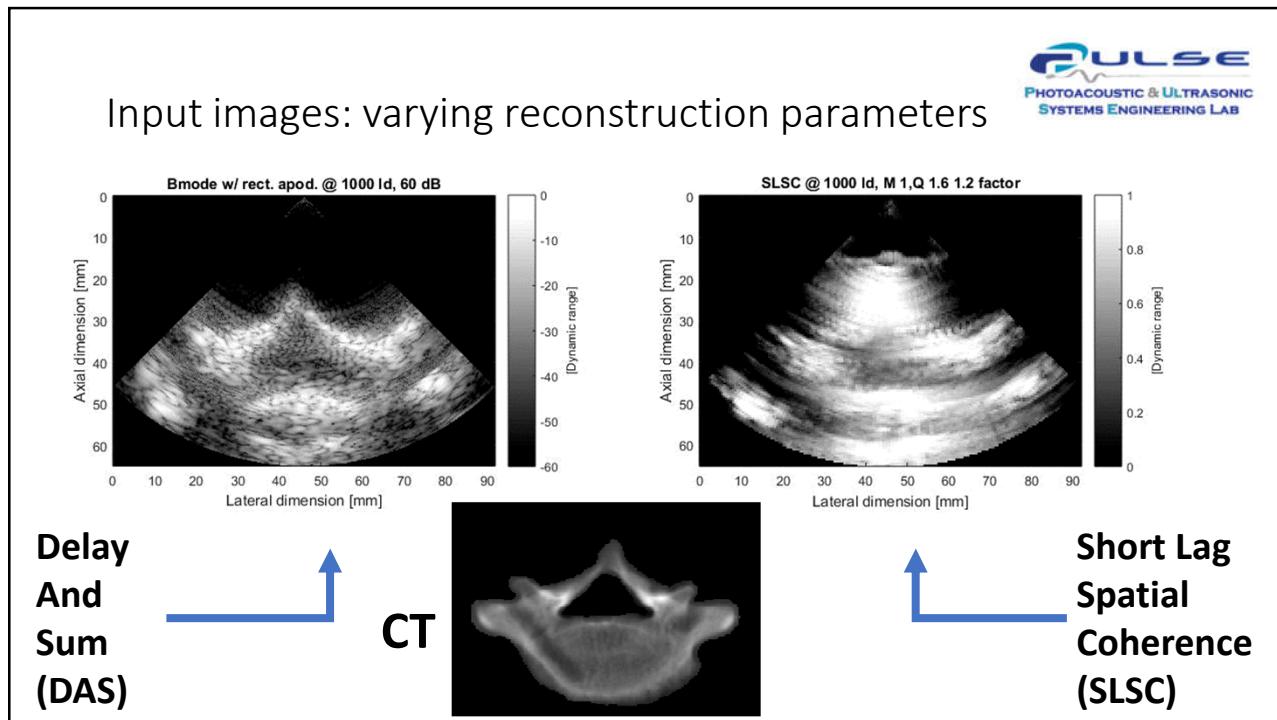


**Goal:** Explore methods to improve accuracy of US-CT image registration through improved US image resolution

Still needs to be tuned







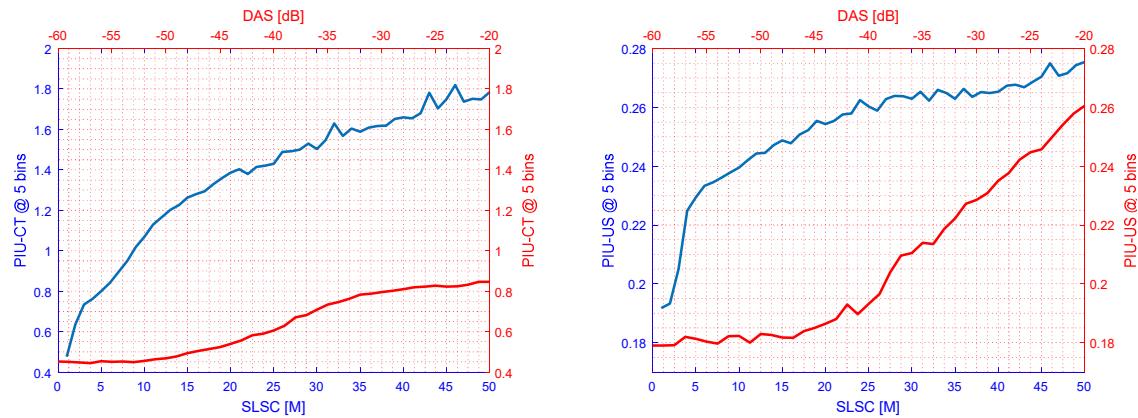
## Metric: Partial Intensity Uniformity



$$\text{PIU}_B = \sum_a \frac{n_a}{N} \frac{\sigma_B(a)}{\mu_B(a)}$$



$$\text{PIU}_A = \sum_b \frac{n_b}{N} \frac{\sigma_A(b)}{\mu_A(b)}$$



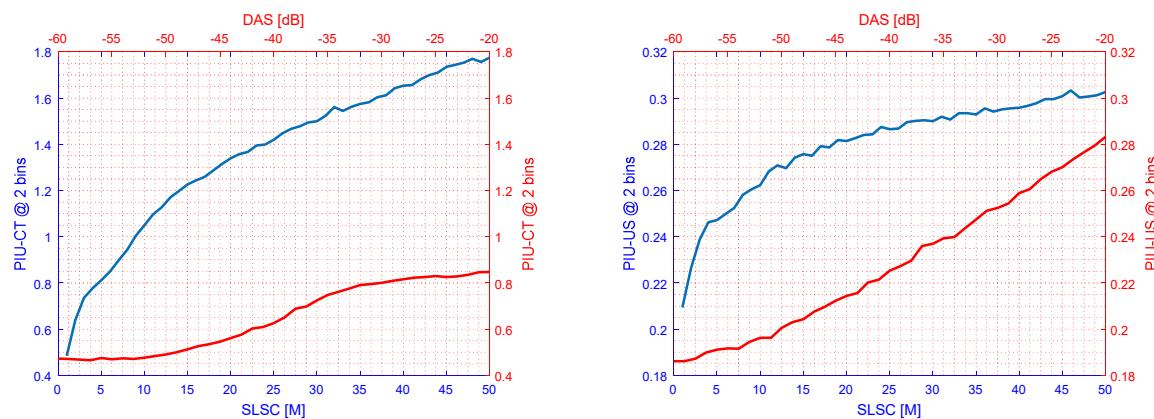
## Metric: Partial Intensity Uniformity



$$\text{PIU}_B = \sum_a \frac{n_a}{N} \frac{\sigma_B(a)}{\mu_B(a)}$$



$$\text{PIU}_A = \sum_b \frac{n_b}{N} \frac{\sigma_A(b)}{\mu_A(b)}$$



## Metric: Mutual Information



$$H(A) = -\sum_a p_A^T(a) \log p_A^T(a) \quad H(B) = -\sum_b p_B^T(b) \log p_B^T(b) \quad H(A, B) = -\sum_a \sum_b p_{AB}^T(a, b) \log p_{AB}^T(a, b)$$

$$H(A) + H(B) - H(A, B)$$



$$\frac{H(A) + H(B)}{H(A, B)}$$



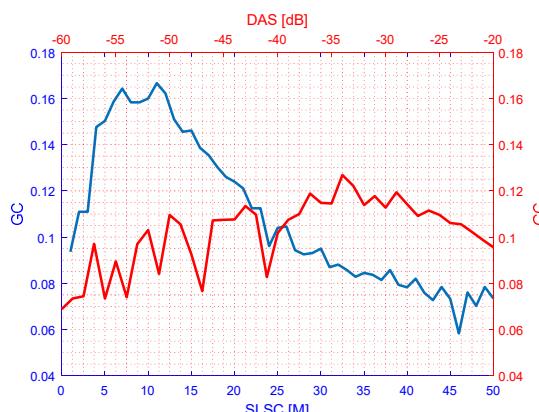
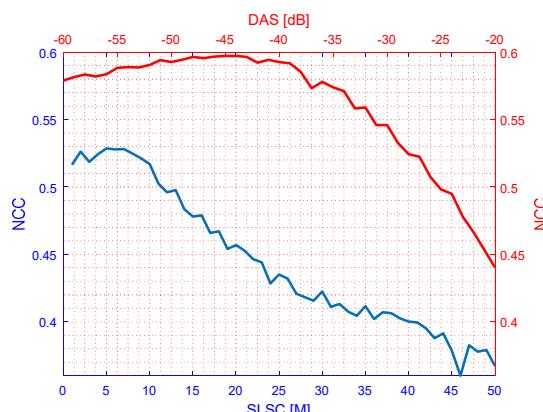
## Metric: Normalized Cross / Gradient correlation



$$NCC = \frac{\sum_{(i,j) \in \Omega^T} [A(i,j) - \bar{A}][B^T(i,j) - \bar{B}]}{\sqrt{\sum_{(i,j) \in \Omega^T} [A(i,j) - \bar{A}]^2 \sum_{(i,j) \in \Omega^T} [B^T(i,j) - \bar{B}]^2}}.$$



$$0.5[NCC(\frac{\partial A(i,j)}{\partial i}, \frac{\partial B(i,j)}{\partial i}) + NCC(\frac{\partial A(i,j)}{\partial j}, \frac{\partial B(i,j)}{\partial j})]$$



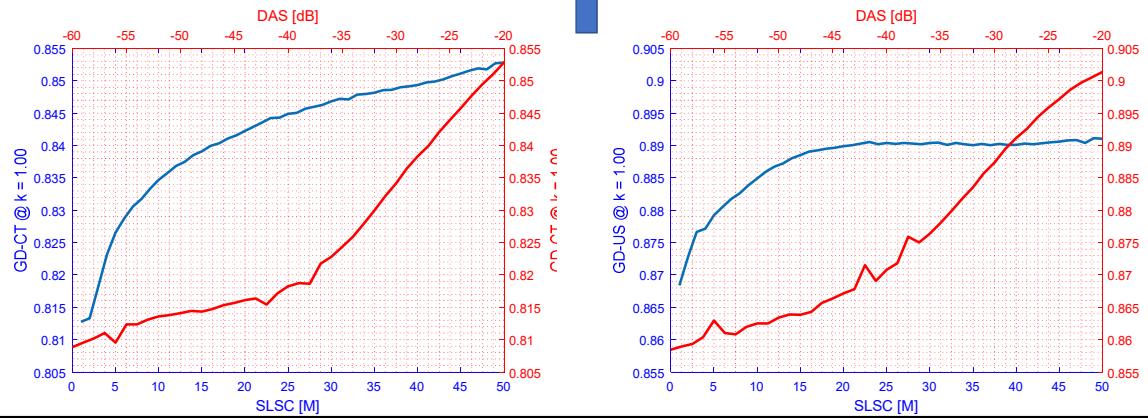
## Metric: Gradient difference



$$GD(k) = \frac{1}{2N} \left( \sum_{i,j} \frac{A_v}{A_v + (I_{difV}(i,j)^2)} + \sum_{i,j} \frac{A_h}{A_h + (I_{difH}(i,j)^2)} \right)$$

$$I_{\text{dif } V}(i,j) = \frac{\partial A(i,j)}{\partial i} - k \frac{\partial B(i,j)}{\partial i},$$

$$I_{\text{dif } H}(i,j) = \frac{\partial A(i,j)}{\partial j} - k \frac{\partial B(i,j)}{\partial j}.$$



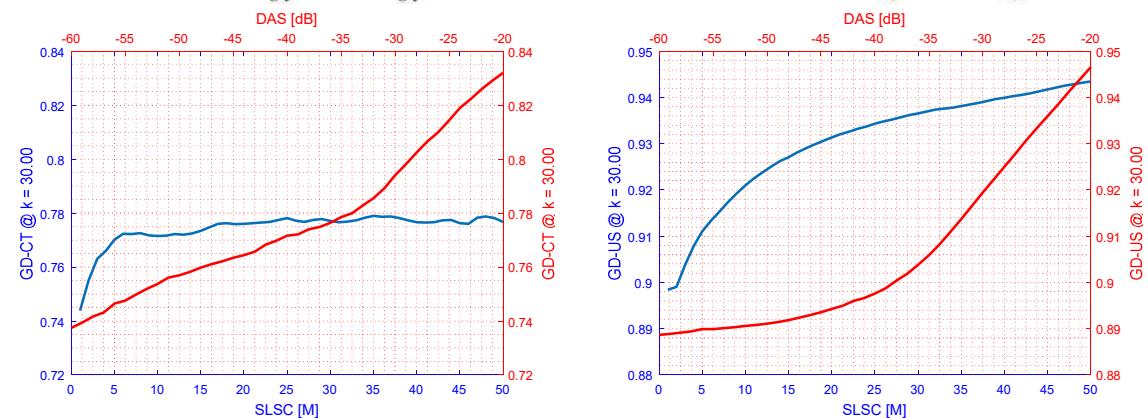
## Metric: Gradient difference

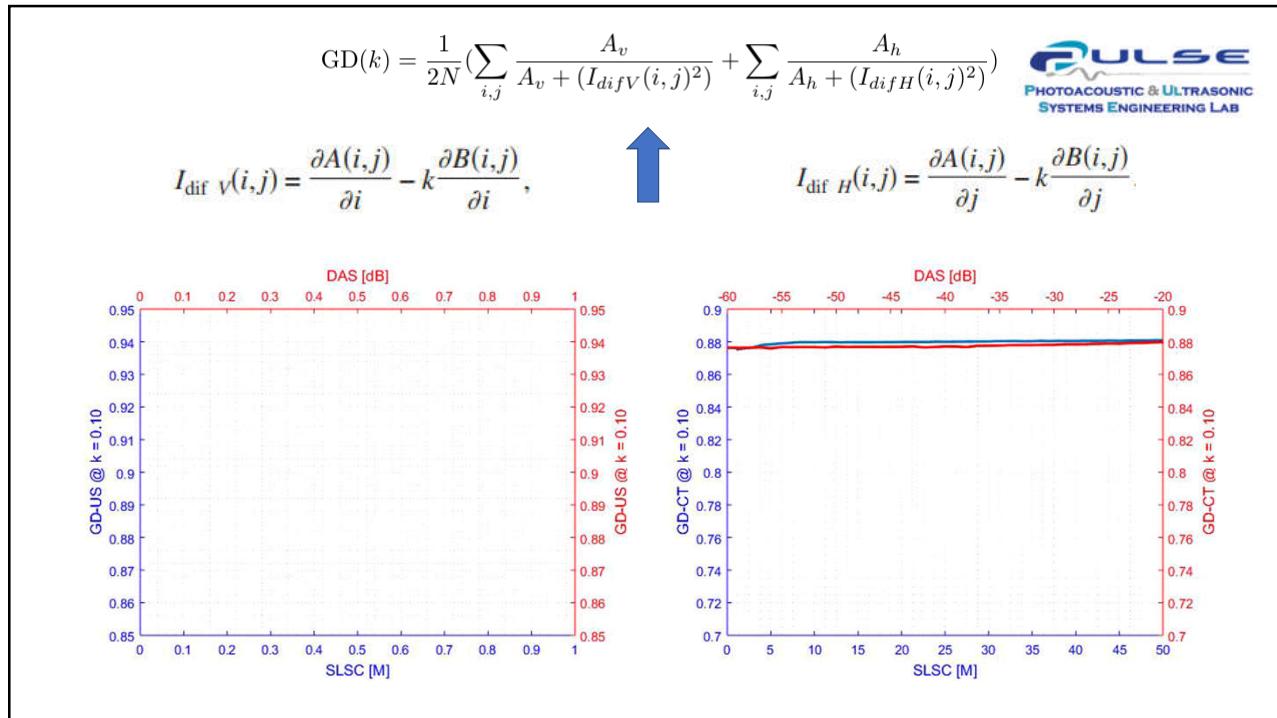


$$GD(k) = \frac{1}{2N} \left( \sum_{i,j} \frac{A_v}{A_v + (I_{difV}(i,j)^2)} + \sum_{i,j} \frac{A_h}{A_h + (I_{difH}(i,j)^2)} \right)$$

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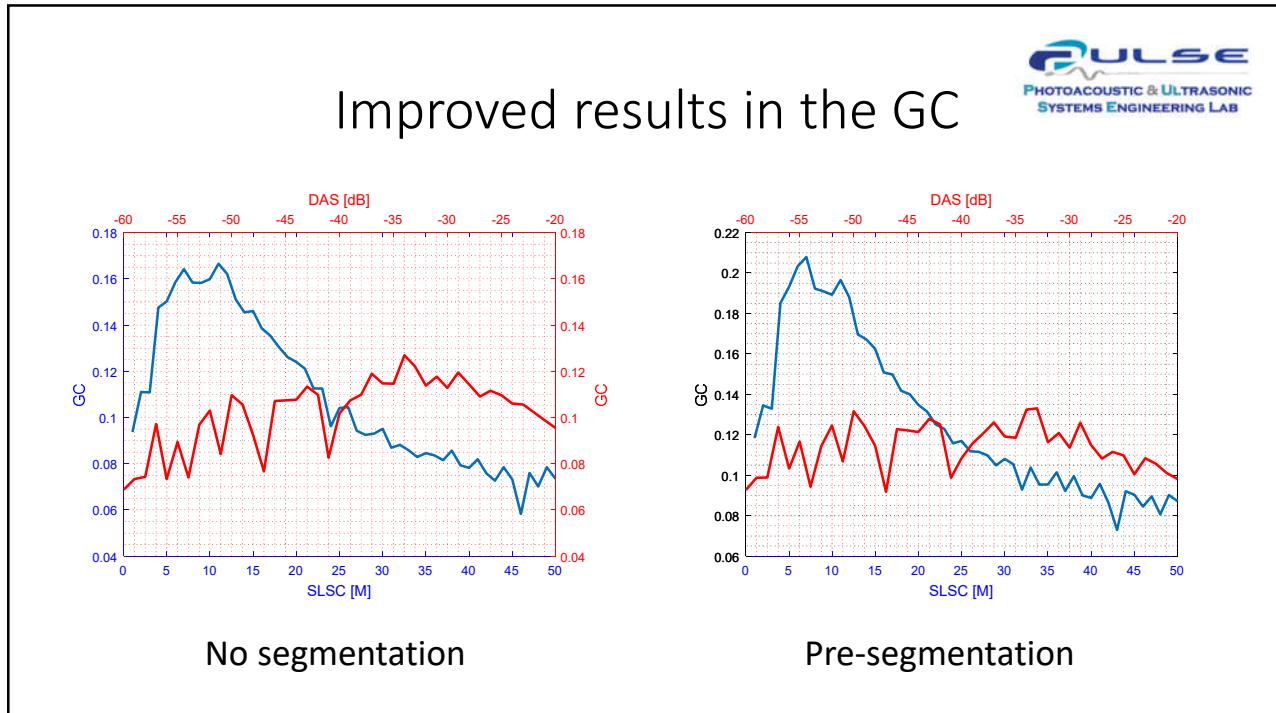
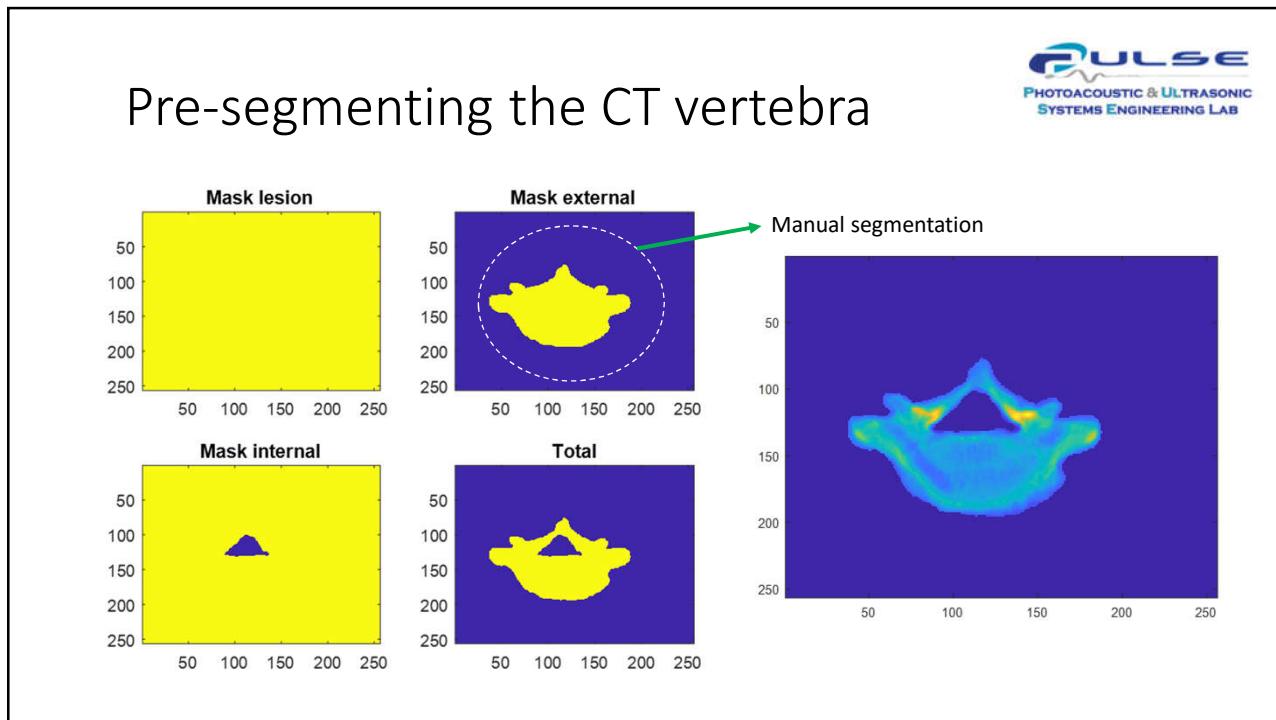
$$I_{\text{dif } H}(i,j) = \frac{\partial A(i,j)}{\partial j} - k \frac{\partial B(i,j)}{\partial j}.$$






  
**LW-SLSC results of selected metric**

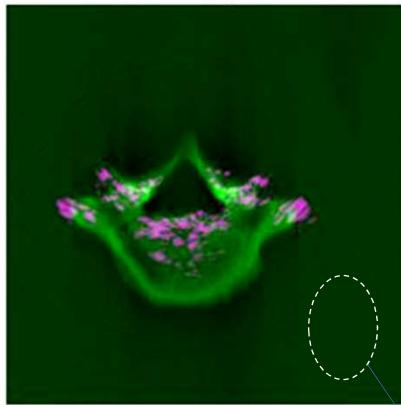
Kx	alpha	OL	GC	GD_CT (1)	GC_US (1)	GC_CT (30)	GC_CT (30)
10	5	0.6	0.2355	0.8416	0.8941	0.7729	0.9288
10	5	0.7	0.2377	0.8417	0.8945	0.7737	0.9291
12	2	0.5	0.2348	0.8392	0.8893	0.7659	0.9237
12	5	0.5	0.2331	0.8401	0.8906	0.7702	0.9257
12	100	0.5	0.1979	0.8458	0.8938	0.7842	0.9341
12	200	0.5	0.1762	0.8471	0.8942	0.7856	0.9359
12	50	0.5	0.2049	0.8452	0.8939	0.7825	0.9327



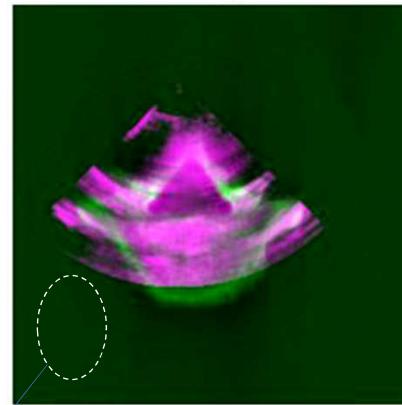
Without segmenting the vertebra at 0  
degrees misalignment

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B-mode @ 20 dB



SLSC @ 1 M

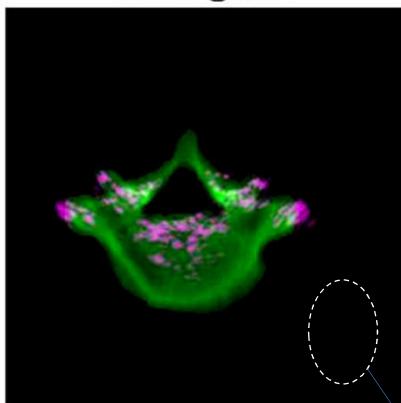


Noisy CT background

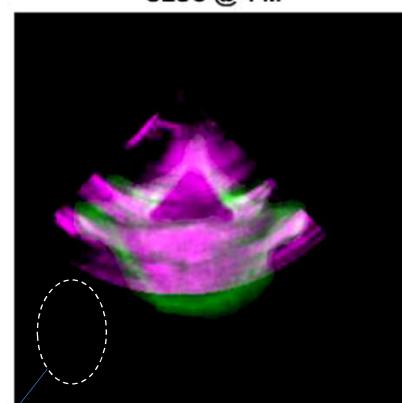
Pre-segmenting the vertebra at 0 degrees  
misalignment

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SYSTEMS ENGINEERING LAB

B-mode @ 20 dB



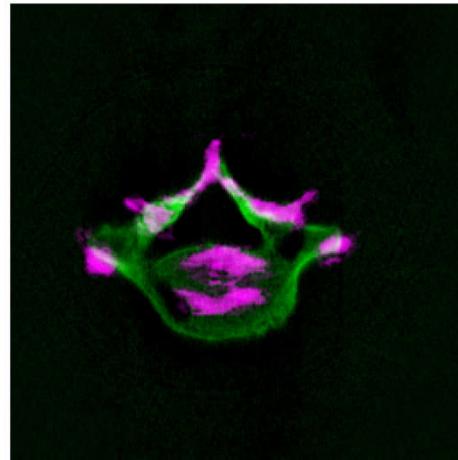
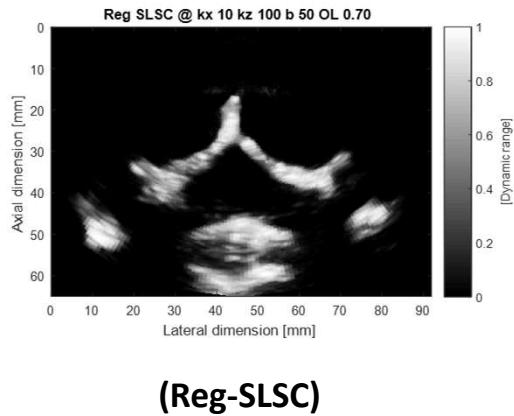
SLSC @ 1 M



No CT background

Pre-segmenting the vertebra at 0 degrees misalignment

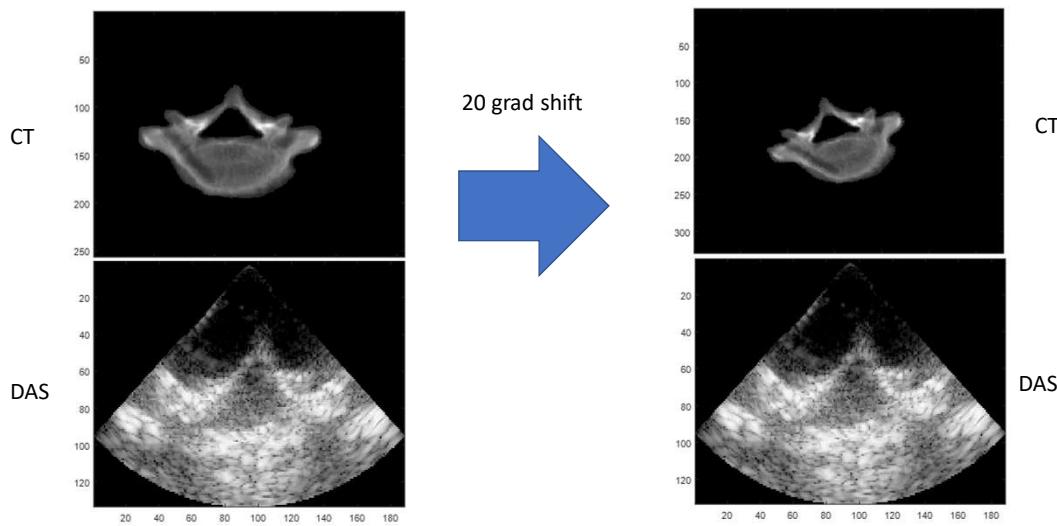
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(Reg-SLSC)

Evaluate what happens if the initial images are not correctly aligned

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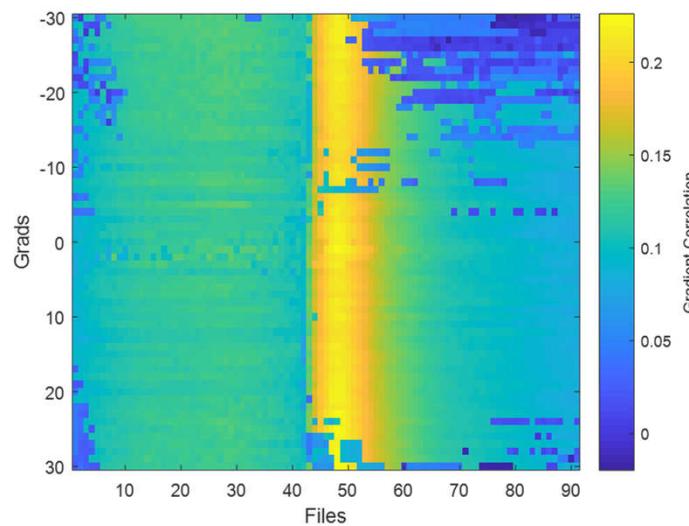
## Current optimizer and metric setup for registration

Optimizer: One plus One Evolutionary		Metric: Mattes Mutual Information	
Maximum Iterations	1 000 000 (not reached)	Number of Bins	8
Grow Factor	1.05	Number spatial samples	500 (not evaluated)
Initial Radius	0.0009	Use All Pixels	true
Epsilon	1.5e-6		

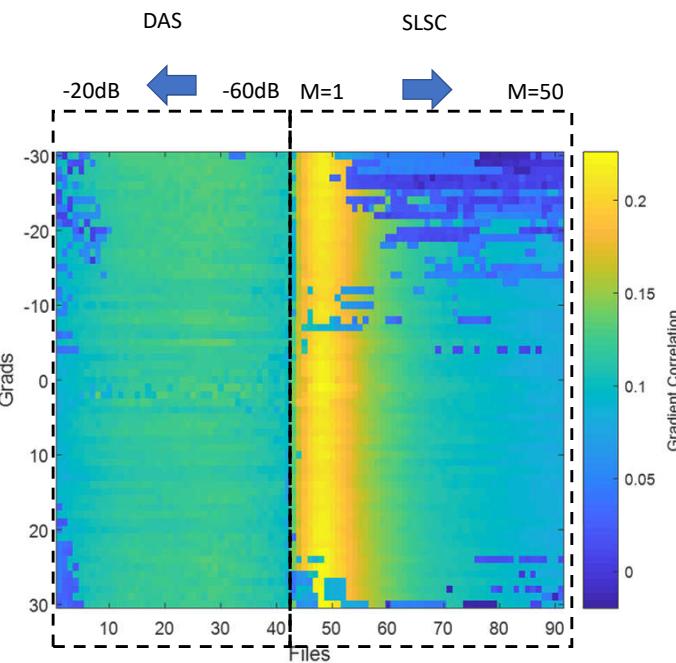
Fixed registration !



## Misalignment results

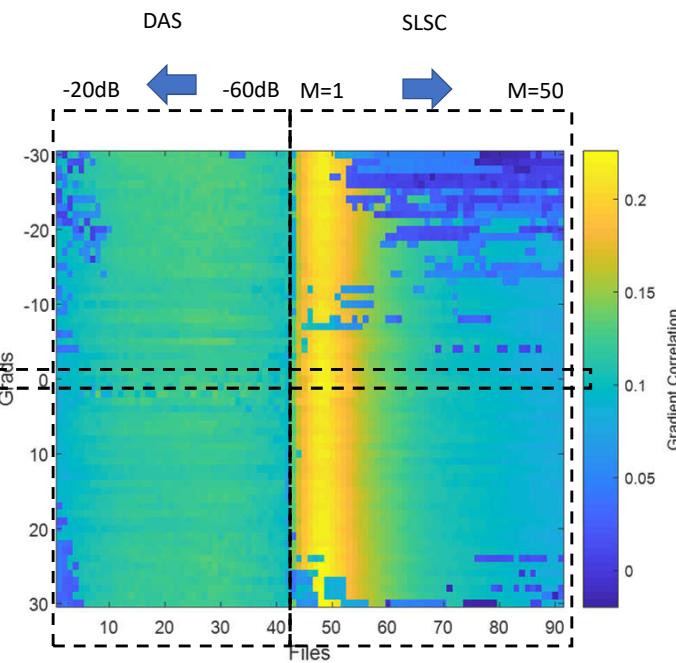


## Results



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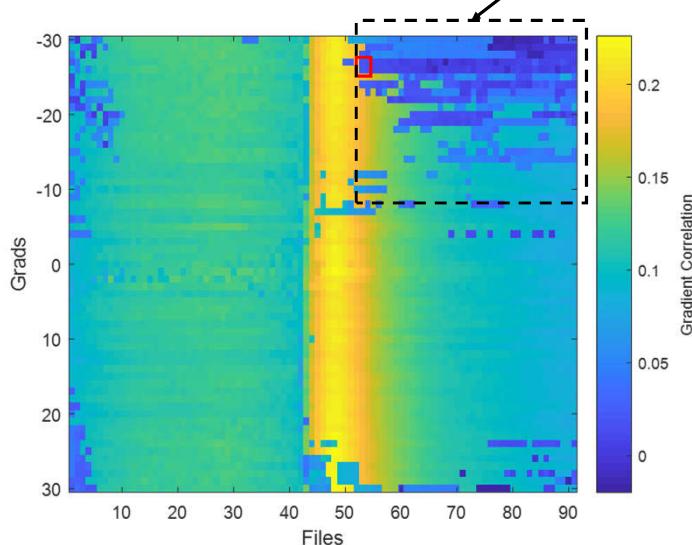
## Results



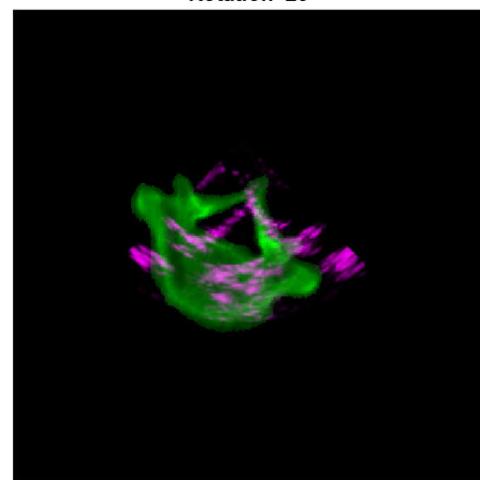
**PULSE**  
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## Results

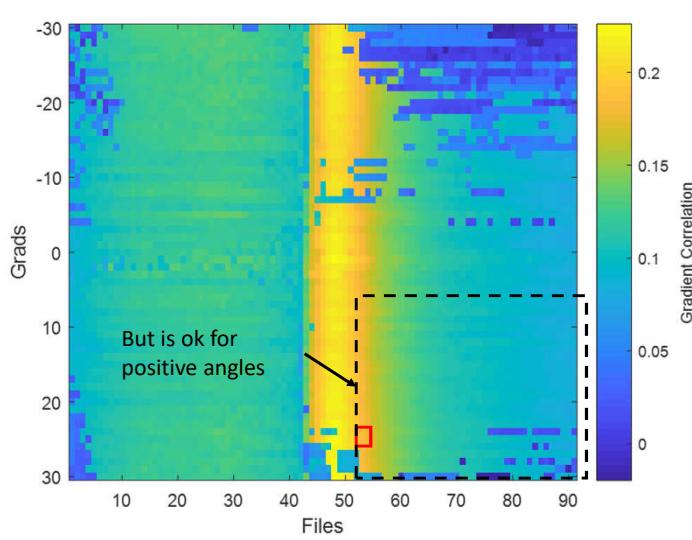
Around M>12 starts to fail for angle <-10



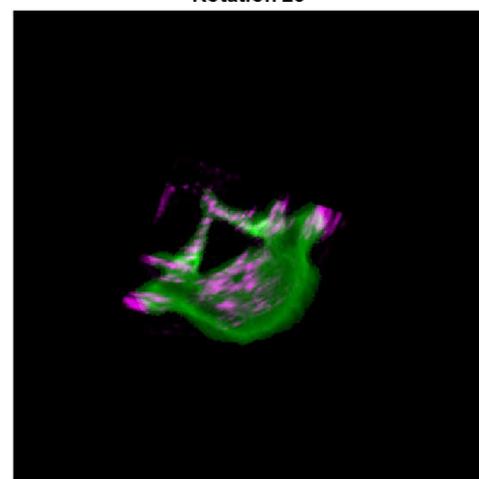
Rotation -26



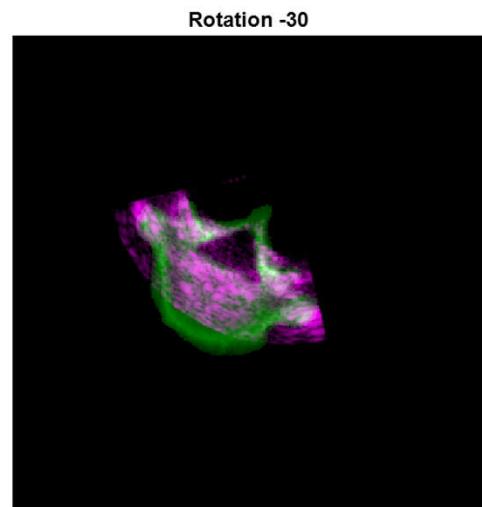
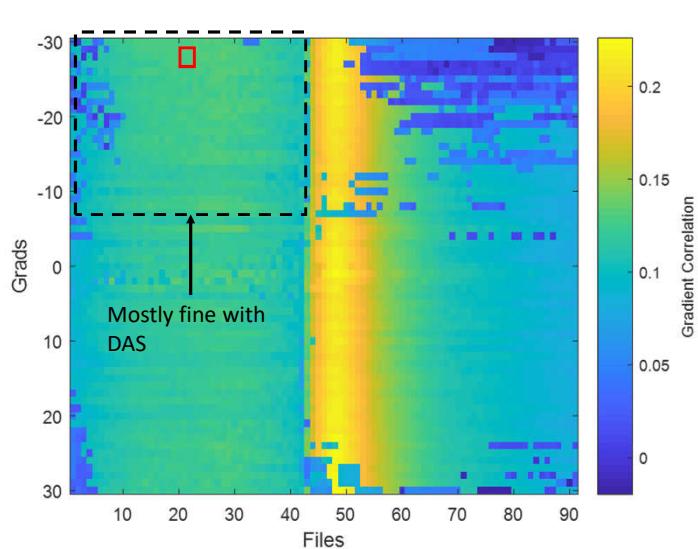
## Misalignment results



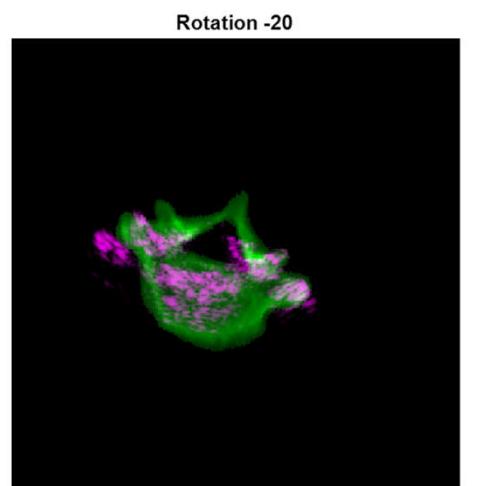
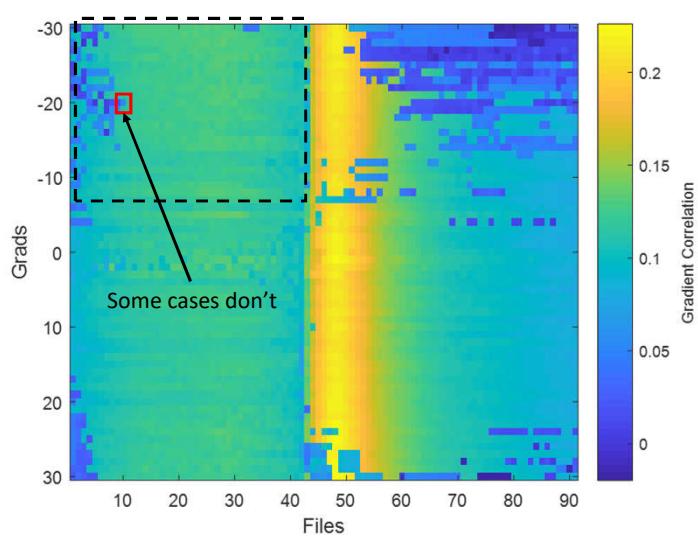
Rotation 26



## Misalignment results



## Misalignment results





## Deliverables

Minimum (March 8 <sup>th</sup> )	Expected (April 5 <sup>th</sup> )	Maximum (April 19 <sup>th</sup> )
<b>Images:</b> Automatic registration of SLSC/DAS US images to CT images of spine specimen (hard tissue)	<b>Images:</b> add robust SLSC to registration framework	<b>Images:</b> add PA to registration framework
<b>Equation:</b> Propose algorithm for a robust SLSC technique		
<b>Graph:</b> Show registration performance when varying quality parameters for SLSC and DAS	<b>Graph:</b> add quality parameters for robust SLSC (e.g., kernel size and regularization parameters)	<b>Graph:</b> compare CT-PA and CT-US registration performance using PA images



## Discussion

- Changing the parameters of the optimizer/metric could potentially improve the registration robustness
- Applying morphological closing could improve the bone structure for SLSC/DAS
- The structure is well defined for Reg-SLSC, therefore should be more robust at high angle deviation



## Conclusion

- More experiments with different metrics and optimizer parameters are needed to verify the robustness of the algorithm with SLSC, Reg-SLSC and DAS images.
- Segmentation of the vertebra is well performed for initial lags of SLSC and all Reg-SLSC, but is poor for DAS images
- Addition of CT markers could be another feature to further test the registration performance



## Weekly work plan

Week	Days	
1	April 2nd-April 6th	Generate L-curve testing for optimal regularization parameter
2	April 9th-April 13th	Implement registration of background article 1 / Compare
3	April 16th-April 20th	Compare registration results with misalignment start
4	April 23rd-April 27th	Test registration performance with CT - markers
5	May 1st-May 5th	Add photoacoustic imaging to the registration framework
6	May 8th-May 12th	Additional processing if needed