

# Checkpoint Presentation: Auto-Segmentation of Spine CT for Data-Intensive Analysis of Surgical Outcome

Group 21  
Ben Ramsay, Niko Eng

## Team Members and Mentors

### Team Members



Ben Ramsay  
*Biomedical Engineering 2018*



Niko Eng  
*Biomedical Engineering 2018*

### Mentors



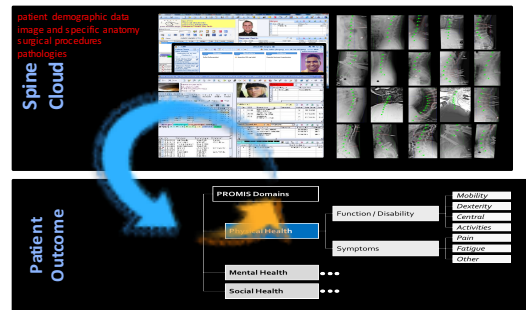
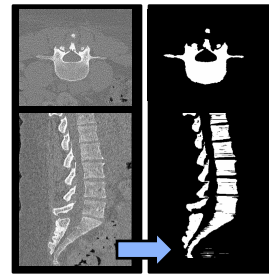
Tharindu De Silva, PhD  
*Post-Doctorate at I-STAR Lab*



Jeffrey Siewerdsen, PhD  
*Professor*  
*Dept. of Biomedical Engineering*  
*Dept. of Computer Science*

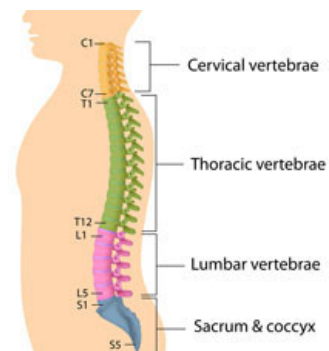
## Motivation and Goals

- Overall: To Develop and Test the “max-flow/min-cut” segmentation method for spine CT images
- “Spine Cloud” – a big data approach to improve spine surgery outcomes
- Correlate defined clinical variables and anatomical quantification to patient surgical outcomes
- Inform future spine surgeries to create more favorable and consistent outcomes



## Original Deliverables

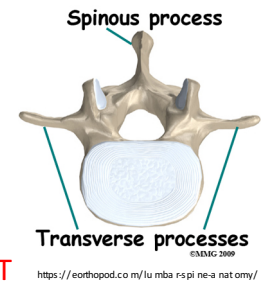
- **Minimum Deliverable:**
  - Assess accuracy of N=20 segmented dataset (L1-L5)
  - Implementation of slice-based Max-flow/Min-cut extended to spine CT
- **Expected Deliverable:**
  - Analysis of Parameter Sensitivity
  - Evaluation of Segmentation Accuracy
  - Generation of a large (N=200) segmented dataset
- **Maximum Deliverable:**
  - Methods for patient-specific parameter selection
  - Methods to accommodate spine anomalies



<https://lowbackpainprogram.com/you-are-lumbar-spine/>

## Updated Deliverables

- **Minimum Deliverable:**
  - Assess accuracy of N=20 segmented dataset
  - **Implementation of 3D Max-flow/Min-cut extended to spine CT**
- **Expected Deliverable:**
  - Analysis of Parameter Sensitivity on N=20
  - Generate and Evaluate Segmentation Accuracy on N=20
  - **Segmentation of (N=200) dataset for Lumbar CT (without Spinous Process)**
- **Maximum Deliverable:**
  - **Segmentation of (N=200) dataset for Lumbar CT with Spinous Process**
  - **Segmentation of (N=200) dataset for Full Spine**
  - **Automatic vertebrae labelling**



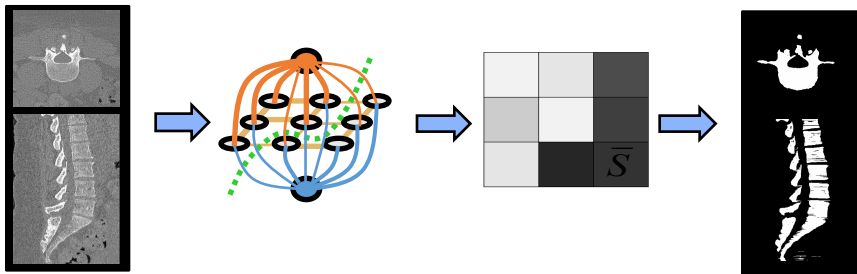
## Original Dependencies

Dependency	Plan to Resolve	Date Expected	Contingency Plan
Access to I-STAR Lab	Gain Access	Completed	-
Workstation / MATLAB	Gain Access / Download	Completed	Remote access using TeamViewer
TCIA Collection (N20 and N200 Datasets)	Obtain from Mentors	Completed	-
Existing Generalized Implementation	Obtain from Mentors	Completed	-
Max Flow / Min Cut Segmentation Method	-	-	Consult Mentors & Explore alternative segmentation methods
Mentor Scheduling	Consult Mentors	Completed (Bi-weekly meetings)	Skype / Accommodate with remote meetings

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Centroid Positions of N20	Obtain from mentors	Completed	-
Centroid Positions of N200	Obtain from mentors	Completed	-

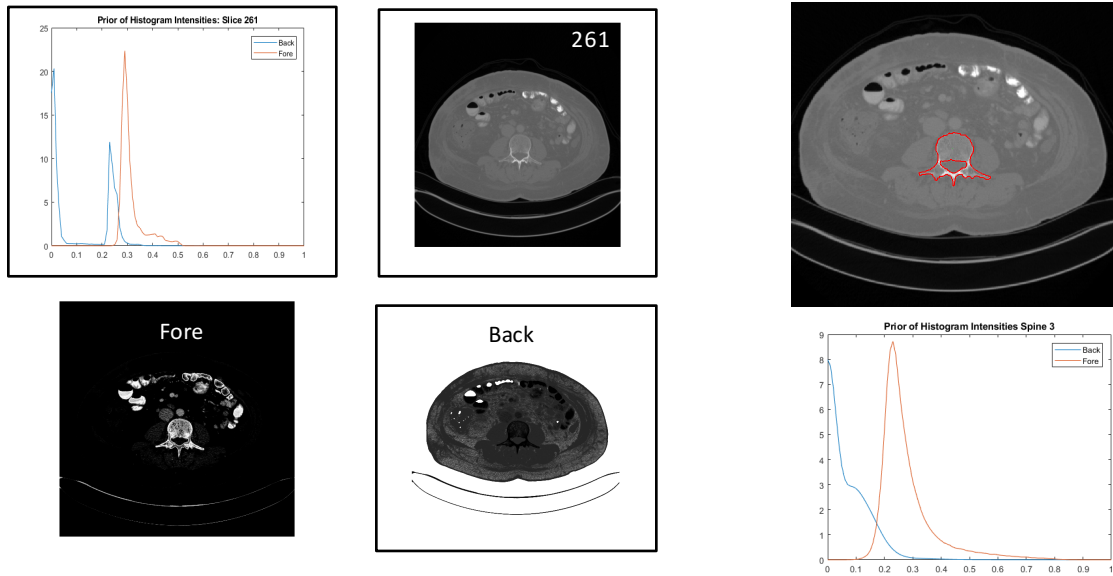
## Graph Cut Explanation



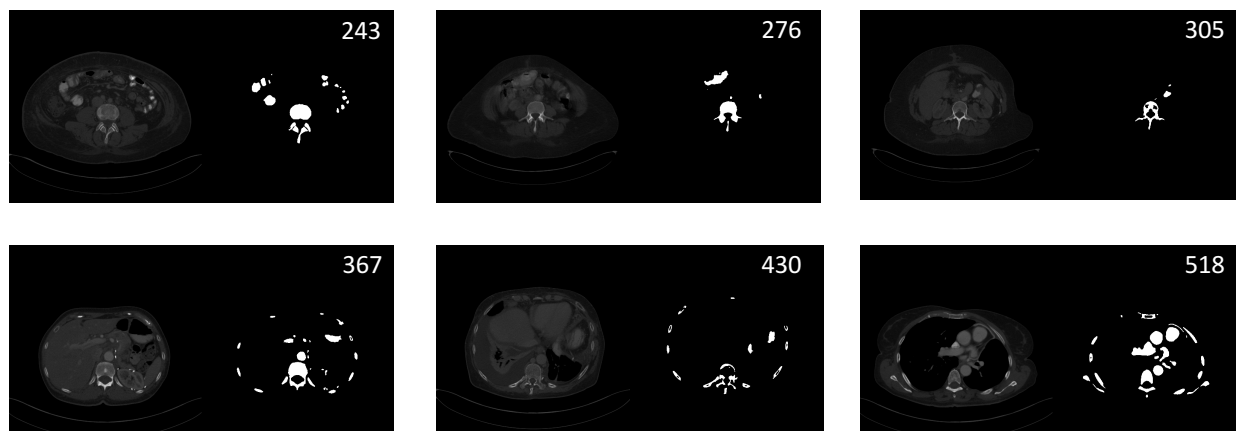
t-links – voxel nodes to terminal nodes  
n-links – voxel nodes to voxel nodes  
Cut defined by minimization of sum of weights

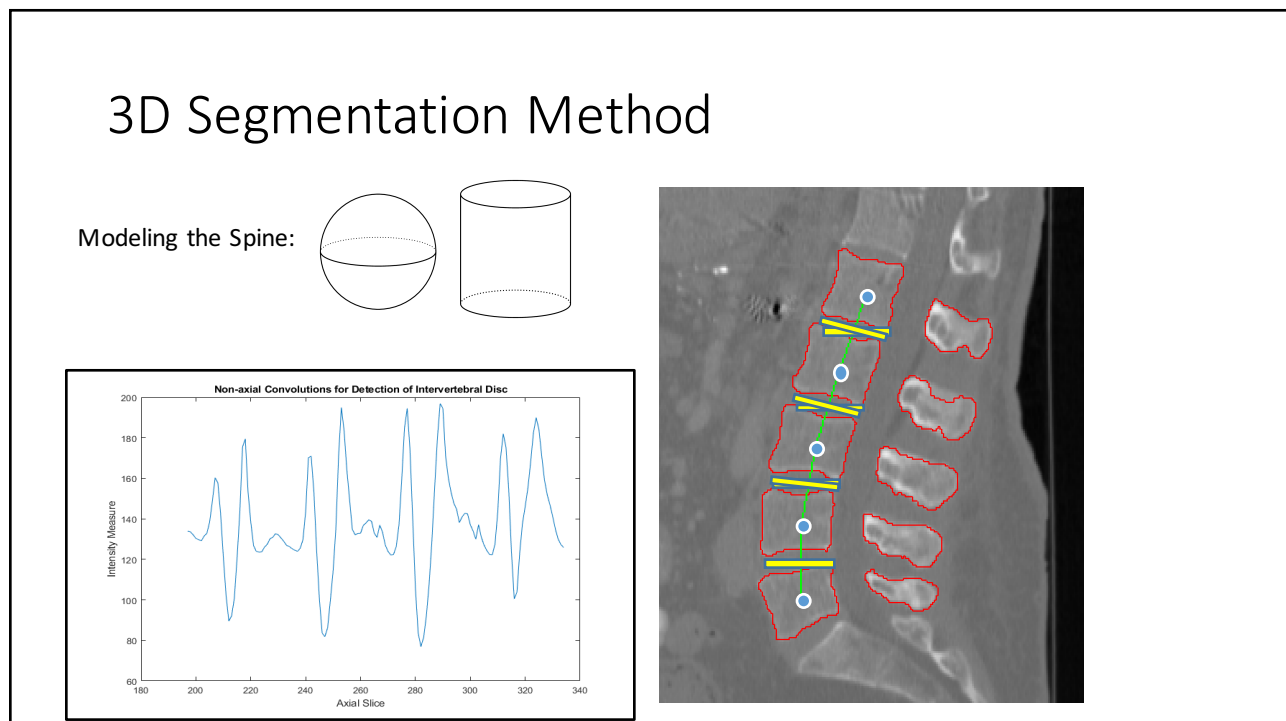
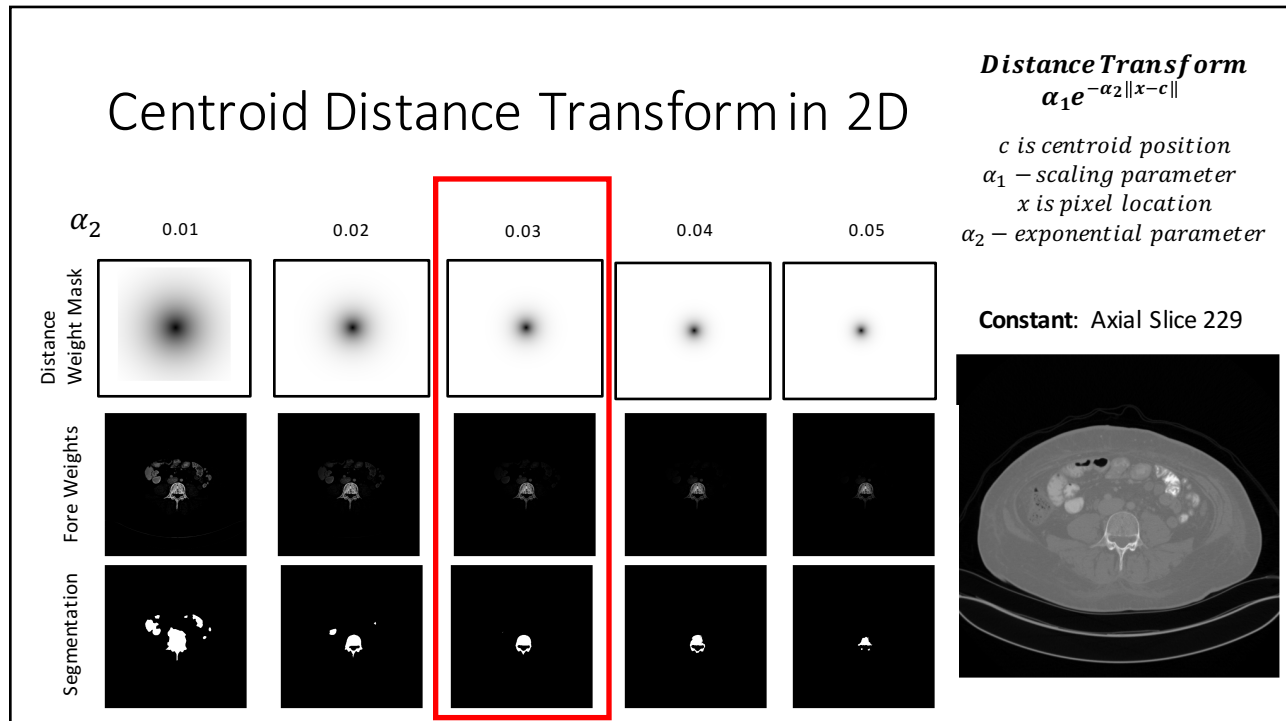


## Pre-Processing / Defining Weights By Intensities



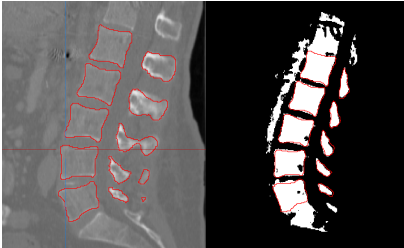
## Basic 2D Segmentation Method Output of N20





## Results

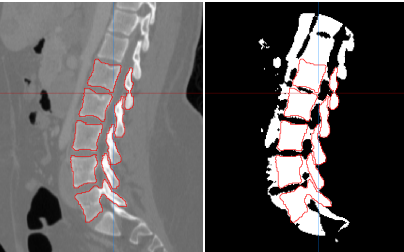
Spine 3



DICE  
0.8318

RMSE  
5.6321 voxels

Spine 22



DICE  
0.6568

RMSE  
22.0022 voxels

### N20 Dataset

- DICE = 0.70426
- RMSE = 14.5667 voxels

### Analysis

- The validation metrics provide limited meaning
  - Only based on Lumbar
- The aorta is being segmented
- Need to tune parameters based on each image
- Impose post processing steps

## Applying to N200

- Pros
  - No aorta
  - Have centroids
  - Clean gradient
- Cons
  - Speckle
  - Different parts of spine

Spine 1



Spine 2



Spine 3



# Project Timeline

		February			March				April				May			
		9	16	23	2	9	16	23	30	6	13	20	27	1	8	15
	Code and Documentation					█	█		█	█			█			█
Pre-Deliverables	Literature Review	█	█													
	Gain Familiarity with 3D Data and Software		█	█												
	Setup workstation in I-Star Lab		█	█												
Minimum Deliverables	Validation of N20 Reference Set			█												
	Max-flow / Min-Cut implementation for Spine			█	█	█										
Expected Deliverables	Analysis of Parameter Sensitivity				█	█	█	█								
	Evaluation of segmentation accuracy				█	█	█	█								
	Segmentation of N200 dataset								█	█	█	█	█			
Maximum Deliverables	Patient-specific parameter selection												█	█	█	█
	Accommodate spine irregularities													█	█	█

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Pre-Deliverables	Literature Review	█	█													
	Gain Familiarity with 3D Data and Software		█	█												
	Setup workstation in I-Star Lab		█	█												
Minimum Deliverables	Validation of N20 Reference Set			█												
	Max-flow / Min-Cut implementation for Spine			█	█	█			█	█						
Expected Deliverables	Implement RMSE & Dice Coefficient				█	█	█	█	█							
	Analyze Parameter Sensitivity on N20					█	█	█	█	█	█	█				
	Implement Distance Weighting							█	█	█	█	█	█			
	Segmentation of N200 Lumbar w/o Spinous Process										█	█	█	█		
Maximum Deliverables	Segmentation of N200 Lumbar with Spinous Process											█	█	█	█	
	Segmentation of N200 Full Spine											█	█	█	█	█
	Accommodate irregularities in N200													█	█	█

## Management Plan

- Biweekly team meetings at I-STAR lab (every other Friday med campus)
- Weekly meetings with Tharindu to go over progress
- Code repository on gitlab for easy / VPN remote access
- Documentation on code, at end we will create user guide



## Reading List

- Yuan, Jing, et al. "A Study on Continuous Max-Flow and Min-Cut Approaches." *2010 IEEE Computer Society Conference on Computer Vision and Pattern Recognition*, 2010
- Boykov, Y.y., and M.-P. Jolly. "Interactive Graph Cuts for Optimal Boundary & Region Segmentation of Objects in N-D Images." *Proceedings Eighth IEEE International Conference on Computer Vision. ICCV 2001*
- Boykov, Yuri, and Vladimir Kolmogorov. "An Experimental Comparison of Min-Cut/Max-Flow Algorithms for Energy Minimization in Vision." *Lecture Notes in Computer Science Energy Minimization Methods in Computer Vision and Pattern Recognition*, 2001, pp. 359–374.

## 2D Segmentation Using Distance Weighting

