

# Project16

## **VR Guided Surgery SDF based guidance and safety**

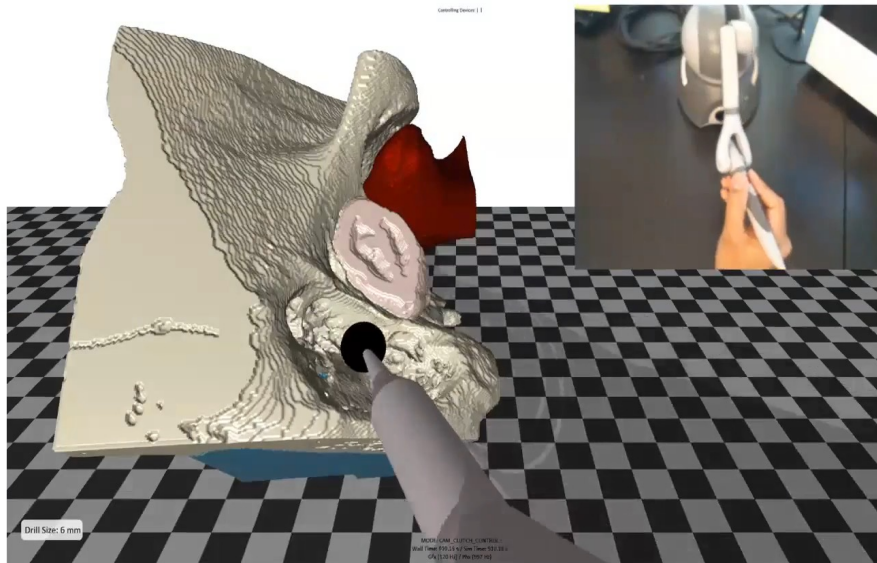
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Mentors: Max Li, Adnan Munawar,  
Prof. Misha Kazhdan, Prof. Russ Taylor

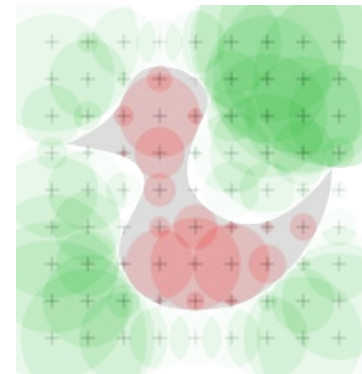


# Project Overview

Goal: Evaluate the effectiveness of feedback modalities based on SDFs to improve situational awareness on virtual drilling



Volumetric Drill Simulation [1]



Signed Distance Field [2]

|     |     |      |      |      |      |      |      |      |      |      |      |      |     |     |     |
|-----|-----|------|------|------|------|------|------|------|------|------|------|------|-----|-----|-----|
| 4.9 | 4.4 | 4.0  | 3.7  | 3.5  | 3.5  | 3.7  | 4.0  | 4.1  | 4.0  | 4.0  | 4.1  | 4.4  | 4.8 | 5.2 | 5.8 |
| 4.1 | 3.5 | 3.0  | 2.7  | 2.5  | 2.5  | 2.7  | 3.0  | 3.2  | 3.0  | 3.0  | 3.2  | 3.5  | 3.9 | 4.4 | 5.0 |
| 3.4 | 2.7 | 2.1  | 1.7  | 1.5  | 1.5  | 1.7  | 2.1  | 2.2  | 2.0  | 2.0  | 2.2  | 2.5  | 3.0 | 3.6 | 4.3 |
| 2.7 | 1.9 | 1.3  | 0.8  | 0.5  | 0.5  | 0.8  | 1.3  | 1.2  | 1.0  | 1.0  | 1.2  | 1.6  | 2.2 | 2.9 | 3.6 |
| 2.1 | 1.3 | 0.5  | -0.1 | -0.5 | -0.5 | -0.1 | 0.5  | 0.3  | 0.0  | 0.0  | 0.3  | 0.8  | 1.4 | 2.2 | 3.0 |
| 1.7 | 0.8 | -0.1 | -0.9 | -1.4 | -1.4 | -0.9 | -0.1 | -0.6 | -1.0 | -1.0 | -0.6 | 0.0  | 0.8 | 1.6 | 2.5 |
| 1.5 | 0.5 | -0.5 | -1.4 | -2.3 | -2.3 | -1.4 | -0.6 | -1.4 | -1.9 | -1.9 | -1.4 | -0.6 | 0.3 | 1.2 | 2.2 |
| 1.5 | 0.5 | -0.5 | -1.4 | -2.3 | -2.3 | -1.4 | -1.0 | -1.9 | -2.8 | -2.8 | -1.9 | -1.0 | 0.0 | 1.0 | 2.0 |
| 1.7 | 0.8 | -0.1 | -0.9 | -1.4 | -1.4 | -0.9 | -1.0 | -1.9 | -2.8 | -2.8 | -1.9 | -1.0 | 0.0 | 1.0 | 2.0 |
| 2.1 | 1.3 | 0.5  | -0.1 | -0.5 | -0.5 | -0.1 | -0.6 | -1.4 | -1.9 | -1.9 | -1.4 | -0.6 | 0.3 | 1.2 | 2.2 |
| 2.7 | 1.9 | 1.3  | 0.8  | 0.5  | 0.5  | 0.8  | 0.0  | -0.6 | -1.0 | -1.0 | -0.6 | 0.0  | 0.8 | 1.6 | 2.5 |
| 3.4 | 2.7 | 2.1  | 1.7  | 1.5  | 1.5  | 1.4  | 0.8  | 0.3  | 0.0  | 0.0  | 0.3  | 0.8  | 1.4 | 2.2 | 3.0 |
| 4.1 | 3.5 | 3.0  | 2.7  | 2.5  | 2.5  | 2.2  | 1.6  | 1.2  | 1.0  | 1.0  | 1.2  | 1.6  | 2.2 | 2.9 | 3.6 |
| 4.9 | 4.4 | 4.0  | 3.7  | 3.5  | 3.5  | 3.0  | 2.5  | 2.2  | 2.0  | 2.0  | 2.2  | 2.5  | 3.0 | 3.6 | 4.3 |
| 5.7 | 5.3 | 4.9  | 4.6  | 4.5  | 4.4  | 3.9  | 3.5  | 3.2  | 3.0  | 3.0  | 3.2  | 3.5  | 3.9 | 4.4 | 5.0 |
| 6.6 | 6.2 | 5.9  | 5.6  | 5.5  | 5.2  | 4.8  | 4.4  | 4.1  | 4.0  | 4.0  | 4.1  | 4.4  | 4.8 | 5.2 | 5.8 |

[1] Munawar, A., Li, Z., Kunjam, P., Nagururu, N., Ding, A.S., Kazanzides, P., Looi, T., Creighton, F.X., Taylor, R.H. and Unberath, M., 2021. Virtual reality for synergistic surgical training and data generation. (<https://www.youtube.com/watch?v=jnonLwxW2Cg>)  
 [2] T. Saito and J.-I. Toriwaki, "New algorithms for euclidean distance transformation of an n-dimensional digitized picture with applications," Pattern Recognition, vol. 27, no. 11, pp. 1551–1565, Nov. 1994, doi: 10.1016/0031-3203(94)90133-3.



# Project Goals and deliverables

**Goal: Evaluate the effectiveness of feedback modalities based on SDFs to improve situational awareness on virtual drilling**

|           | <b>Deliverable</b>  |
|-----------|---|
| Minimum   | Creating an AMBF plugin to calculate SDFs for static objects in the volumetric drilling simulation.   |
| Expected  | Develop SDF based feedback modalities to improve situational awareness. <ul style="list-style-type: none"><li>• Developing haptic based feedback modalities.</li><li>• Developing visual based feedback modalities.</li></ul> |
| Maximum 1 | Internal user study and/or conference paper.  |
| Maximum 2 | Optimizing algorithms to calculate SDFs of objects changing overtime in real-time, e.g., the drilling volume.   |



# Project phases

## 1. SDF for static volumes (Offline SDF calculation)

~Mar. 14/12

- a) Familiarize with methods to calculate the signed distance fields.  
(<https://github.com/mkazhdan/EDT>)
- b) Integrate SDF functions with AMBF using plugins.

## 2. Use SDF to improve situational awareness of the user.

~Apr. 27

- a) Provide Visual feedback.
- b) Haptic Feedback.
- c) Perform a user study (optional).

## 3. SDF for changing volumes (Online SDF calculation)

~May. 17

- a) Optimizing algorithms to calculate SDF for volumes that change over time



# Dependencies

| Dependency                    | Status                             | Fallback/Prevention                       | Needed by  | Effect                                |
|-------------------------------|------------------------------------|---|------------|---------------------------------------|
| Access to a Linux workstation | Obtained                           | N/A                                       | 02/18/2022 | Delay in all milestones.              |
| Access to haptic device       | <del>In progress</del><br>Obtained | Focus only on visual feedback mechanisms. | 03/23/2022 | Delay in haptic feedback development. |
| IRB approval                  | In progress                        | N/A                                       | 03/31/2022 | Delay in internal user study.         |
| VR device                     | Obtained                           | Using 2D screen                           | 03/31/2022 | Delay in internal user study.         |



# Project phases

## 1. SDF for static volumes (Offline SDF calculation)

~Mar. 14

- a) Familiarize with methods to calculate the Euclidean Distance Transform. (<https://github.com/mkazhdan/EDT>)
- b) Integrate SDF functions with AMBF using plugins.

## 2. Use SDF to improve situational awareness of the user.

~Apr. 27

- a) Provide Visual feedback.
- b) Haptic Feedback.
- c) Perform a user study (optional).

## 3. SDF for changing volumes (Online SDF calculation)

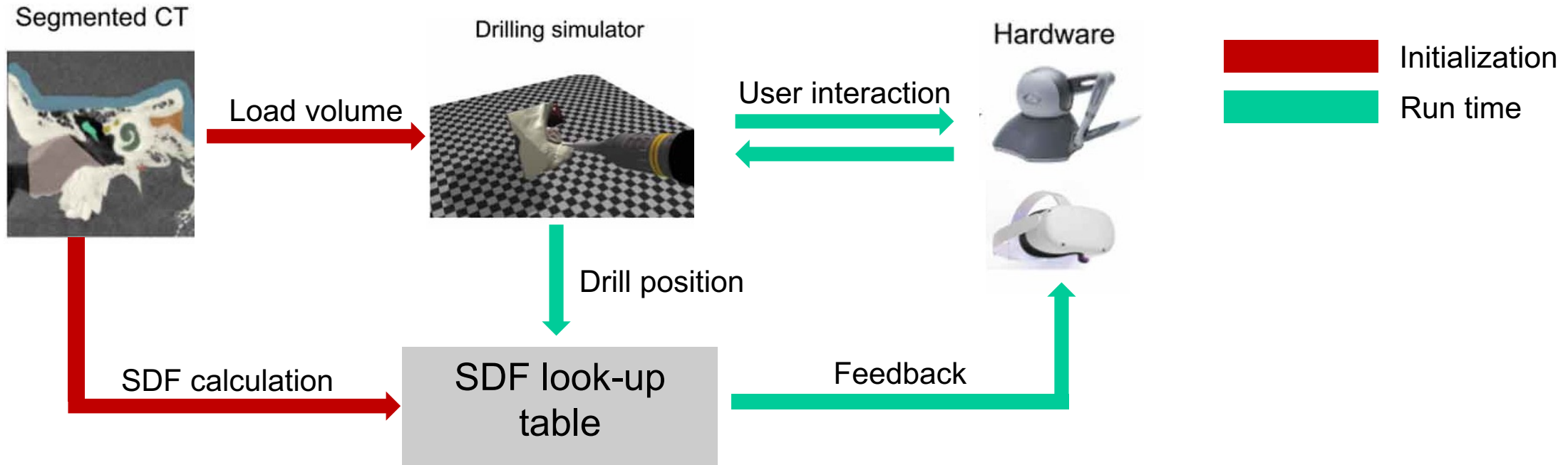
~May. 17

- a) Optimizing algorithms to calculate SDF for volumes that change over time



# Technical overview

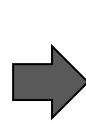
- Phase 1: SDF calculation for static objects & software integration architecture.



- SDF calculation for volumes represented by a voxel grid based on [Saito and Toriwaki, 1994][2].
- SDF functions will be loaded as a shared library to AMBF.

# Technical overview: Offline calculation of SDF

Anatomy representation

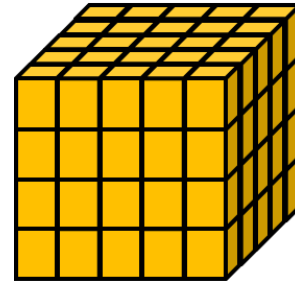


SDF  
module

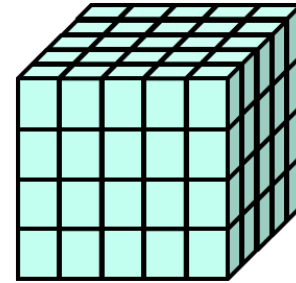


SDF maps for each anatomical structure.

V0

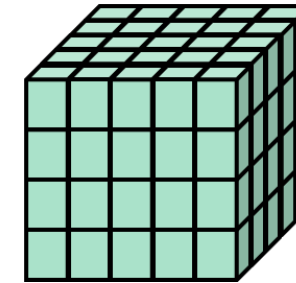


V1

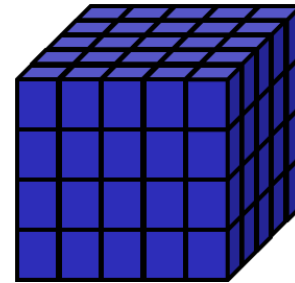


...

V15



V16



SDF look up table

Design parameters

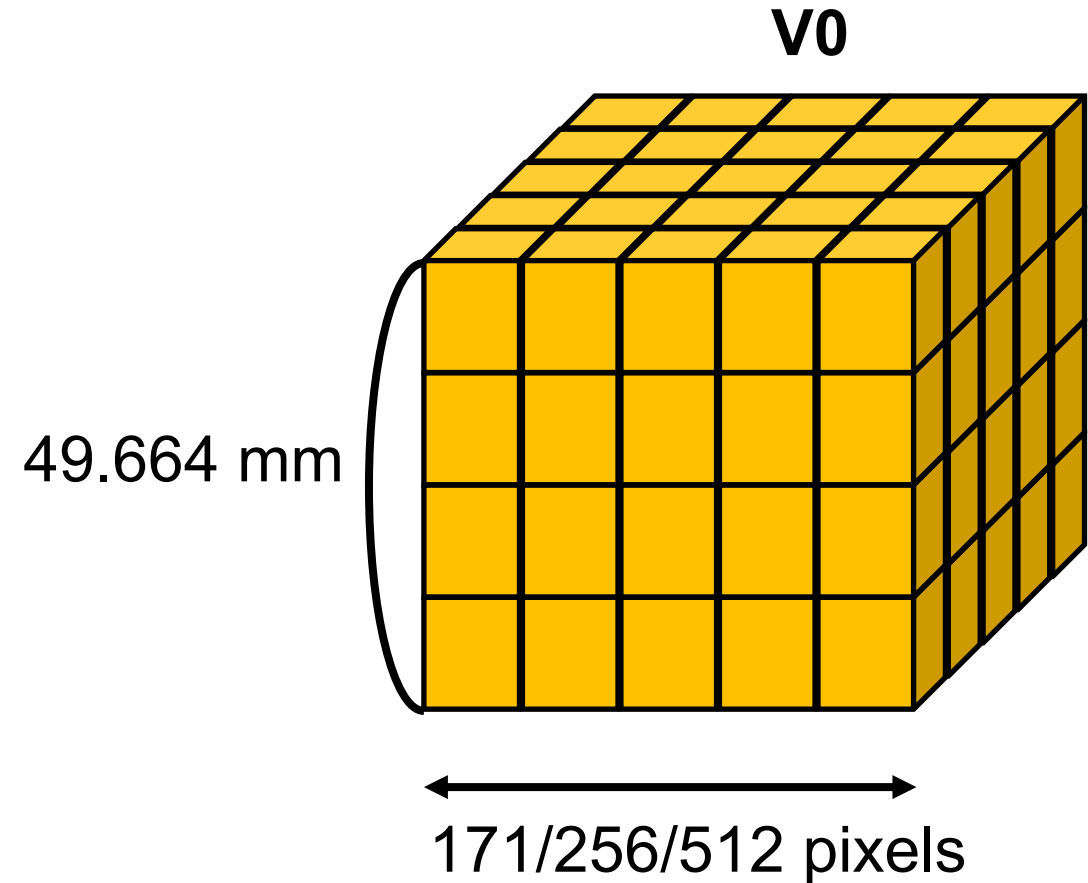
- 16 different anatomical structures
- SDF Resolution 171/256/512
- Size SDF cube: 49.664 mm<sup>3</sup>
- Zero-padding: 0



# Technical overview: Offline calculation of SDF

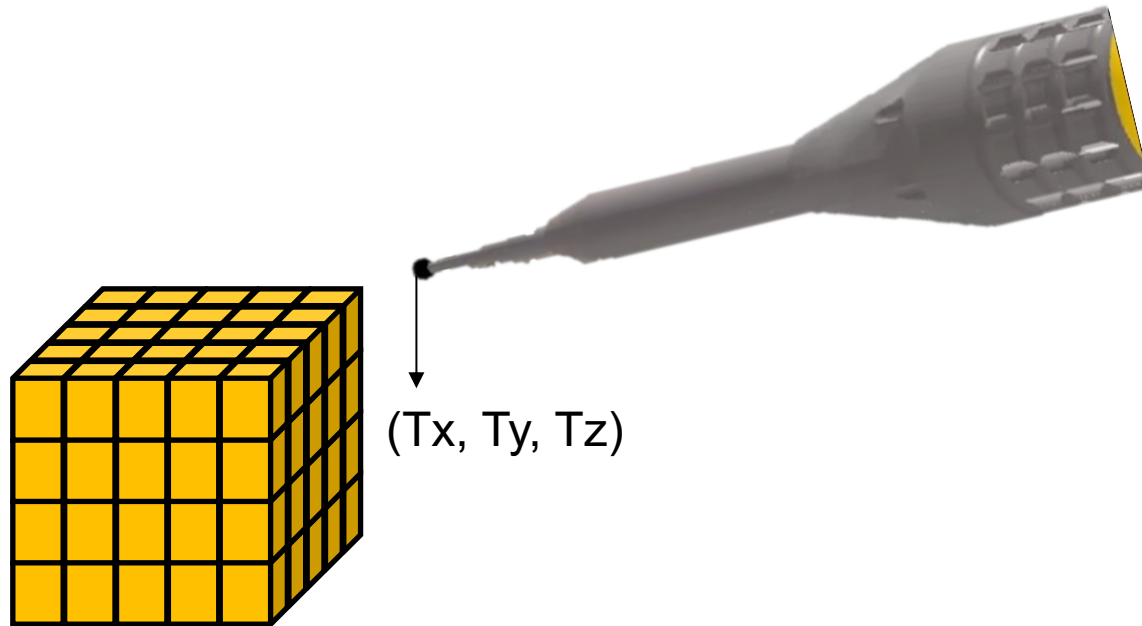
## Design parameters

- SDF Resolution 171/256/512
- Size SDF cube: 49.664 mm
- Zero-padding: 0



# Technical overview: Using SDF at runtime.

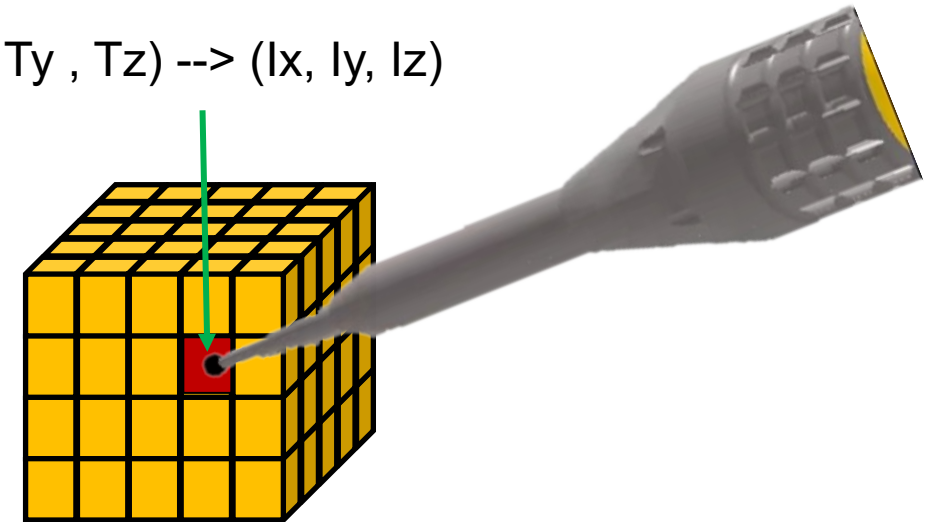
Outside the SDF grid



- No distance information when drill tooltip is outside of SDF grid.

Inside the SDF grid

$(T_x, T_y, T_z) \rightarrow (I_x, I_y, I_z)$

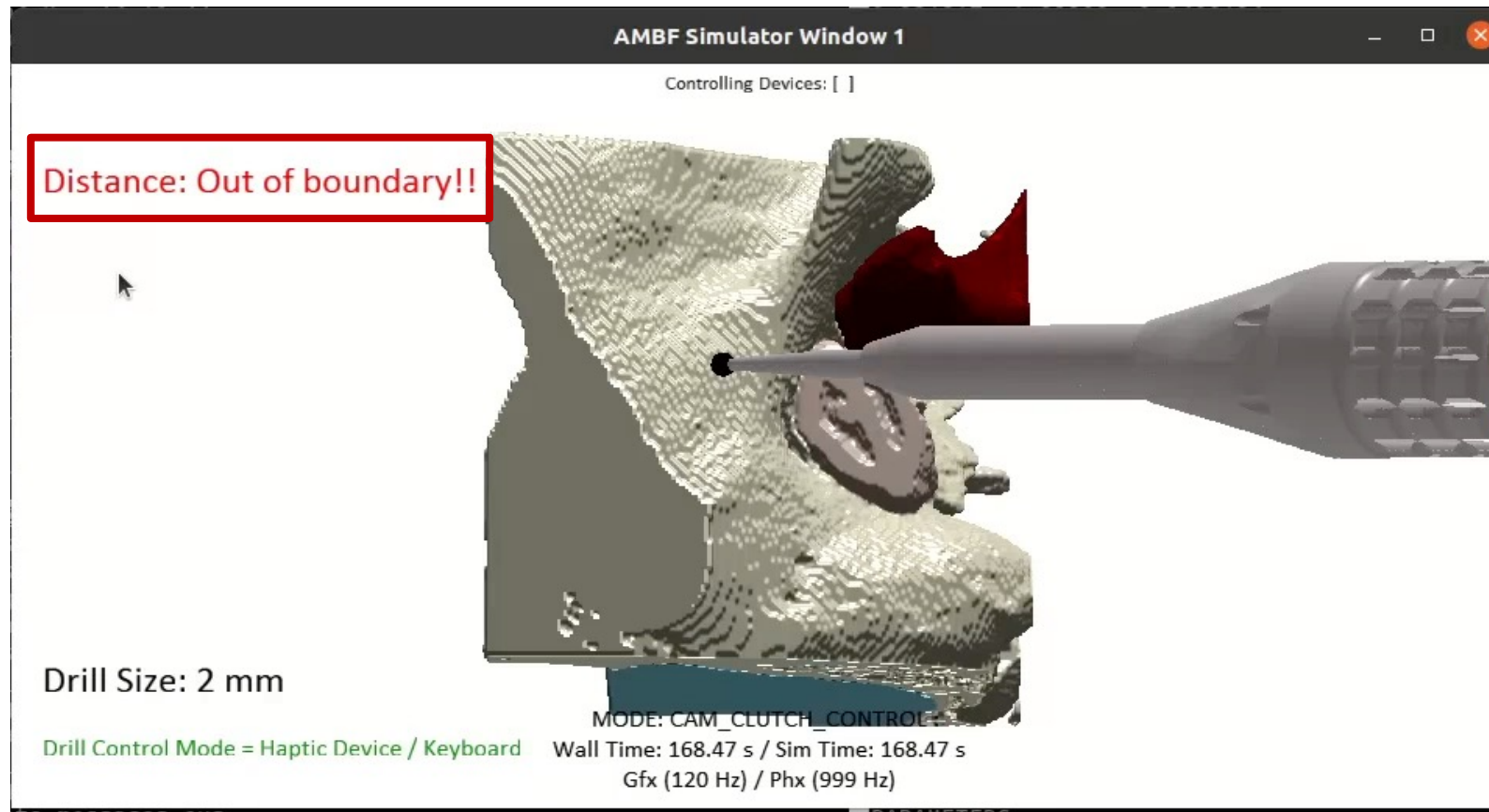


- When inside the grid a conversion between tooltip coordinates and voxel grid index is needed to access the distance data.



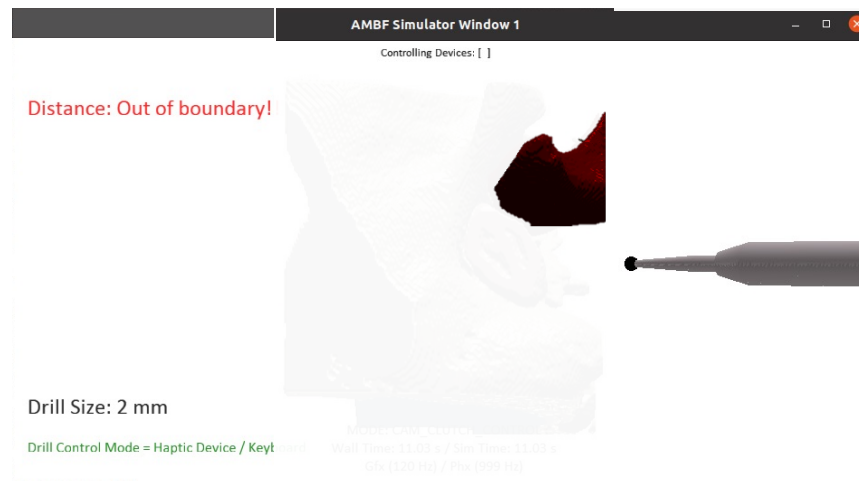
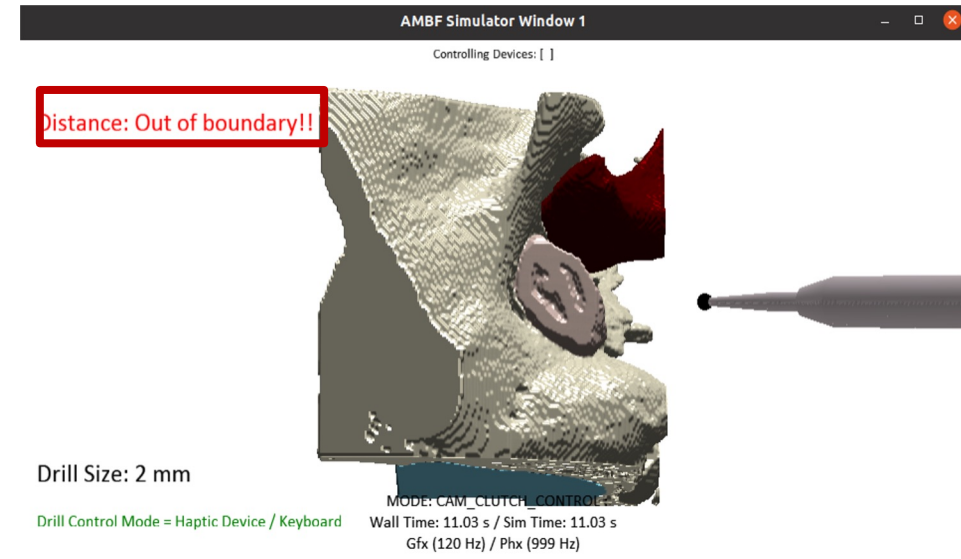
# Current Progress

- Provide distance between Tool tip and the critical structure(blue)
  - SDF resolution: 171
  - Controlled using keyboard



# Current problems

- Limited SDF workspace
  - Expand the size of volume(zero-padding)
  - Find the appropriate SDF resolution
- ➔ **Important parameters for Online SDF calculation(Phase3)**
- Effective visual feedback
  - Toggle the opacity of the bone and highlight the critical structure



# Next steps

## 1. SDF for static volumes (Offline SDF calculation)

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## 3. SDF for changing volumes (Online SDF calculation)

~May. 17

- a) Optimizing algorithms to calculate SDF for volumes that change over time



# Updated Gantt chart

