# Voice Control of *da Vinci*® Checkpoint Presentation

Lindsey Dean and H. Shawn Xu April 26, 2011

Mentor: Anton Deguet

1



### Background

- The da Vinci<sup>®</sup> is a robotic teleoperated surgical system
- Controlled by surgeon at HD workstation with hands and feet

PROBLEM: Complex gestures, stop-start procedures

#### SOLUTION: Allow surgeon to control certain parts of the system via voice



#### Background (continued)





#### Dependencies

	Status	Planned Date	Date Accomplished
Access to Mock OR	x	2/21	2/28
Signed NDA with Intuitive	x	2/21	2/28
Account on DaVinci PC	x	2/27	3/3
Software Installation: Sphinx4 (w/ C++ wrappers), ITK, CISST libraries, 3DUI, DaVinci Wrappers, Robotorium	x	3/12	3/28
Anton's Time	-Has been very dependable and believe will continue to be so	Cont. through 4/26	4/26
Voice Package Functioning on PC		Mid–April (Next Week)	4/21



# **Completed Tasks**

- We have met our minimum deliverable.
- We have successfully built our first demo (to be shown tomorrow at 9:30AM)
  - Allows surgeon to control 3DUI with voice



# Logic of Demo





#### **Milestones & Progress**

	Milestone	Status	Planned	New Expected	Accomplish ed
$\checkmark$	Overcome logistical dependencies		2/27		2/28
$\checkmark$	Ready for Software Architecting		3/17		3/28
$\checkmark$	Approved Documentation of Software Framework		3/23		4/10
$\checkmark$	Working Demo of Voice Control of DaVinci	Live demo on 9/27 at 9:00AM	4/17		4/25
	Incremental improvement of first voice demo				
	Wrap up all coding - produce final report		5/15		



## Design

- Three separate components
  - da Vinci®
  - 3D User Interface
  - Voice Recognition
- Our demo will be a 4<sup>th</sup> internal component (voice user interface)
- It will
  - Define contexts
  - Define grammars for each context
  - Listen for events from voice recognition
  - If input is defined in current context, either change context or communicate with *da Vinci*<sup>®</sup> or 3DUI
- Easy to add/modify behaviors: simply change context/grammar definition and change links between provided and required interfaces



# Voice Control of CISST 3D-UI



#### **Current Status**

- Solved previous difficulties
- Sphinx 4 on Windows
  - Tinkered with configuration
  - Still not perfect, but working well enough for proofof-concept demonstration
- Shared vs. static library conflict on Windows
  Problem solved (THANKS ANTON)



# **Moving Forward**

- Clean up logic
  - Currently a lot of the behavior logic is very confusing (was meant for 3DUI)
  - We hope to refactor the code so that adding additional functionality or connecting other components is more intuitive
- Implement additional functionality
  - Connect with *da Vinci*<sup>®</sup> console/arms directly
    - Control camera?
    - Select which arms the console controls?



# **Deliverables Unchanged**

- Minimum (100%)
- Well-documented demo program that adds singular functionality
  - A video demonstration of voice control
  - Expected (75%)
    - Additional features in demo program that show different functions voice can perform on *da Vinci*<sup>®</sup>
  - ► Maximum (→0%)
    - Fully-functioning library of states and commands that can be easily expanded upon



#### Timeline

	Feb 20	Feb 27	Mar 6	Mar 13		Mar 27	Apr 3	Apr 10	Apr 17	Apr 24		May 1	May 8	May 15
Exploration														
Initial Design														
Implementation														
Get separate pieces working					Spi									
Combine pieces					ring Br						Today			
Build 1 <sup>st</sup> demonstration					eak									
Analyze/modify														
Add additional functionality														
Document														
Final Paper & Presentation														



## Summary

- We are excited to have met our minimum deliverable, a working demo of voice control on the *da Vinci*<sup>®</sup>
- After tomorrow's live demo, we will continue to add functionality



# Thank You!

