

# Voice Control of Da Vinci

Lindsey A Dean and H. Shawn Xu

Mentors: Anton Deguet

## Goals:

- Integrate voice control with the *da Vinci*® surgical robot for control of peripheral features

## Significance:

- Proof of concept that voice is a viable and appropriate interface to controlling some functionality

## Results:

- Demo that allows user to measure distance and create 3-D map of marks using voice.

