Enhanced Simulation for the daVinci System





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Recap Slide!

- Develop a simulation framework for the daVinci System using Open Source dependencies (except ISI API)
 - CISST-SAW^[5,6] (developed at ERC-CISST, JHU)
 - H3DAPI ^[7]



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Recap (cont'd)



Significance:

- Develop new object models and newer applications
- Generate ground truth easily
- Patient specific simulation for procedural planning

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[1] Robotic Surgery Training with Commercially Available Simulation Systems in 2011: A Current Review and Practice Pattern Survey from the Society of Urologic Robotic Surgeons

Costas Journa

Reviews the existing (2011) robotic surgical simulators!

[2] Current Status of Validation for Robotic Surgery Simulators – A Systematic Review



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Relevance

- Good to have knowledge of the competitive technology in surgical simulation (robotic)
- Surveys involved provide insight on needs of the surgical society
- In final form, this project would need a validation study too!

Terminology

- Face Validation
 - Extent to which examination resembles the situation in real world
- Content Validation
 - Extent to which intended content domain is being measured by the assessment exercise
- Construct Validation
 - Extent to which a test measures the trait it purports to measure





daVinci Skills Simulator: Anastomosis Task (Tubes)

daVinci Surgical System: Anastomosis task^[3]

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Terminology (cont'd)

- Concurrent Validation
 - Extent to which results of a test correlate with the gold standard
- Predictive Validation
 - Extent to which an assessment will predict future performance

	Perf	ormance Evaluation	on	
Exercise	Report Exercise History	Metric History		
		Guest		
Exercise: Pick & Place		r	Overall Score	
Attempt:	6	Overall Score		
Date - Time:	11/15/2010 - 09:01:20	97%	100 F	
Critical errors: 0		Detailed Report	20	
		Results per Metric	effer	gi [*] ³ ⁶
Time to Comple	te ExerciseEconomy of Motion		Decessive Instrument ForceIn	struments Out Of View
×		\checkmark	×	\checkmark
38.1 s	ec 99.9 cm	0	0 sec	0 sec
Andreas and a second se				
L	Master Work	space Range - Drops -		
L hardening	- Masser Work	space Range - Drops -		
Luccum	- Master Work	Icm		

Mscore – automated skill assessment^[4]

- OSATS (Likert scale 1-5)
 - Respect for Tissue
 - Time and Motion
 - Instrument Handling
 - Flow of Operation
 - Knowledge of Procedure

OSATS - subjective skill assessment

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Robotic Surgical Simulator (RoSS)^[5]



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Simsurgery Educational Platform (SEP)^[6,7]



SEP Basic Robot Place Arrow

www.SimSurgery.com

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LapVR^[8]





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dV-Trainer^[9]



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daVinci Skills Simulator (dVSS)^[4]





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Materials and Methods

- Both papers performed a MEDLINE literature search with keywords:
 - Robotic surgery
 - Simulation
 - Virtual Reality

- Validation Studies
- [1], also sent out a blinded survey to members of the Endourological Society regarding training and VR simulation
- [2], additionally searched in EMBASE, PsychINFO, EAU, AUA databases

Comparison of Simulators^[1,2]

Simulator	RoSS	SEP	dV-Trainer	dVSS
Hardware	Comparable to actual console	No console, monitor, arm board, CPU	Desktop w/ simulated pedals on floor	Actual Si console with backpack
Face Validation				
Content Validation		√		√
Construct Validation				
Procedural Modules	HOST (Hands-On Surgical Training)	(Laproscopic Simulator)		
Cost (additional annual service)	\$120,000	\$62,000	\$158,000	\$89,000 (without console)

Properties of Simulators^[1,2]

- All contain certain attributes:
 - Stand-alone simulator independent of vision cart and robot
 - Vision monitor for user/tutor to critique
 - Minimal cost of operation (no consumables required)
 - Relative freedom from operating room
- Some exceptions

- Utilization of the daVinci Si console in case of dVSS
- HOST technology of RoSS
- Absence of camera, clutching, fourth arm, needle control, energy dissection in SEP

VR Simulation Survey ^[1]

- Sex, Age, Surgical discipline, Experience
- Awareness/access robotic surgery simulation
- If access:
 - Type of simulator
 - Education Program Curriculum
 - Source of funding for purchase
- Reasonable Cost?
- Role in Training
- Largest obstacle

Responses ^[1]

- Only 65 out of the ~ 1200 recipients responded
- Demographics (fairly representative):
 - Majority males
 - > 40% in practice over 15 years
 - ~ 75% were involved in training
- Simulator:

- ~ 25% have access to simulator at their institute
- Majority have dVSS (released in 2011!)
- > 90% believed in an expanding/advanced role in training
- > 80% consider current pricing unreasonable

Discussion on Validation Studies^[2]

- Lack of standardization of metrics to measure simulator quality
 - scale for face validation, definition of expertise
- Scale of the studies remains small (max 46 subjects)
- Variability and inconsistency in statistical methods
- Parameters like concurrent validity, predictive validity, feasibility, reliability have not been evaluated

Issues with Robotic VR Simulators ^[1,2]

- Absence of Procedural components
 - HOST, only such application on RoSS that takes the trainee through a virtual procedure while keeping them engaged on the console
 - No evidence of improving performance in real-setting!
- High Cost

- Concerns magnified with the annual maintenance fee
- Departmental funding limited
- Surgeons are happy with current training curricula
- Not incorporated at large scale at institutions

Limitations of the Reviews ^[1,2]

- May have missed some relevant validation studies
- Paucity of reports related to:
 - Head-to-head comparison of VR simulators
 - Several components of simulator like cost effectiveness
- Formal analytical results not possible due to different measurements for studies
- VR simulation as part of surgical training still to be determined!

Critique

- Extensive search of literature
- [2], first of a kind review
- Excellent job of explaining the existing simulators
- Both papers conclude with the need for
 - Procedure based simulation
 - Complex skill evaluations
 - Large scale validations
 - Low cost simulations

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Thank you!

Questions?



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