Synthetic Aperture Ultrasound Imaging with Robotic Tracking Technique Haichong Kai Zhang, Ezgi Ergun

Mentors: Dr. Emad Boctor, Xiaoyu Guo, Alexis Cheng

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4 - 6

Distance (mm)

Goals:

• The goal is to achieve higher resolution through robotic synthetic aperture ultrasound imaging.

Significance:

- Overcome the limitation of ultrasound image resolution restricted by physical size of US transducer.
- Enable to visualize deep sight in high resolution.

Results:

- 1mm accuracy ultrasound calibration
- 2. Synthetic aperture algorithm development and simulation evaluation
- Experimental validation 3.











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