#### Group 21: Robotic Soft Tissue Assessment Checkpoint Presentation

Team Members: Syed Hossain, Bugrahan Cigdemoglu Mentors: Paul Wilkening, Yunus Sevimli, Dr. Russ Taylor, Dr. Lee Akst, Dr. Chris Razavi





# Overview

- Project Summary
- Progress
- Timeline
- Dependencies





# **Project Summary**

 Assess and prove through expert analysis that robotic assisted laryngeal surgery is more effective than mere manual surgery



Figure 1: Microlaryngeal Phonosurgery





## **Project Summary**

 Use GALEN robot to assist in the laryngeal cyst removal surgery in animal larynx to mimic real surgery







## In discussion with mentors



- Option 2:
- Virtual fixture approach on 2D model to mimic a laryngeal surgery





# **Option 1 Details**







## **Option 2 Details**







# **HIRB Protocol**

- Submitted draft
  - Received feedback from Dr. Akst and Dr. Taylor
    - Meeting with Dr. Taylor and Yunus between 10-11am to edit IRB
    - Phone call with Dr. Akst for final advice/touchups at 3:30pm on Friday
      - Submit Final IRB version on Friday EOB





## More on HIRB

- 4 participants
  - 2 surgeons
  - 2 students
    - We believe two would be a good sample for each category
    - We also would like 2 students since we believe they would be less experienced, and may add more variability to our data





### **Updated Deliverables**

#### Minimum

- I. Study design for surgery, data collection and analysis  $\checkmark$
- II. Questionnaire design for tremor, efficiency (time), and tissue damage ✓
- III. Videotape of surgical experiments on animal vocal cord conducted by experts with and without robotic assistance
- IV. Results and analysis of the questionnaire filled by experts

#### Expected

- I. Simple video analysis algorithm using Matlab/Python to quantify tremor in vocal cyst removal surgery videotape
- II. Videotape of surgical experiments on animal vocal cord conducted by med students with and without robotic assistance
- III. Results and analysis of the questionnaire filled by experts
- IV. Results of tremor analysis in all videotapes using the algorithm

#### Maximum

- I. 3D virtual fixture algorithm developed for the robot using C++
- II. Study design for conducting robotically-assisted surgery with virtual fixtures
- III. Videotape robotically-assisted surgical experiments with virtual fixtures on the phantom conducted by experts
- IV. Comparison of questionnaire and tremor analysis results of non-assisted, robotically-assisted with no virtual fixtures, and robotically-assisted with virtual fixtures surgeries on the phantom





### **Updated Timeline**

UPDATED SCHEDULE	Feb W4	Mar W1	Mar W2	Mar W3	Mar W4	Mar W5	Apr W1	Apr W2	Apr W3	Apr W4	May W1	May W2
Minimum												
Plan Presentation												
Design experiment procedure												
Discuss experiment options w/ experts												
Prepare and submit HIRB forms												
Project Checkpoint Presentation												
Setup expert meetings												
Conduct surgery with experts												
Conduct questionnarie on surgery												
Analyze survey results												
Expected												
Develop quantitative tremor analysis algo												
Conduct surgery with med students												
Conduct questionnarie on surgery												
Quantitative analysis of the video of surgeons and med students												
Analyze survey and quantitiave results												
Maximum												
Setup expert meetings												
Develop VF algorithm												
Conduct surgery with experts												
Compare results with past experiments												
Prepare Poster												
Project Final Presentation												





# **Updated Dependencies**

Dependency	Resolution
Use Matlab for video hand tremor analysis	Add a different colored dot on surgical equipment
Mock OR access	Access granted
Receive HIRB approval	In-progress: Submit on March 31
Procure animal larynx for experiment	In progress: Email sent to Yunuscan Sevimli
Get experts to conduct experiment Apr W2	In progress: Request sent to experts
Get med students to conduct experiment Apr W3	In progress: Request email to be sent on Apr W1
Get experts to conduct experiment May W1	In progress: Request email to be sent on Apr W2
Get permission to experiment with animals	Meet with Yunuscan Sevimli
ROS background for virtual fixture algorithm	Meet with Paul Wilkening



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