Data Collection System for Smart Endoscope Project

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Mentors:

Dr. Russell Taylor Dr. Masaru Ishii Dr. Chien-ming Huang





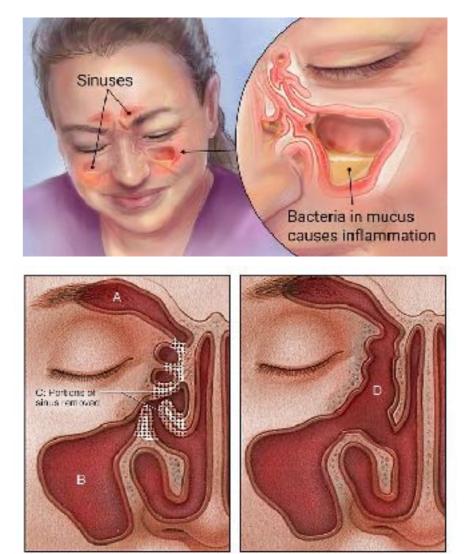






Background

- What is Sinusitis?
- What is Sinus Surgery? [2]
 - Traditional
 - Ballon
 - Endoscopic(FESS)



Before surgery

After surgery M/WO 0/101

DRAFD RECEIVED FOR PARAMENDARION AND HIGHARDER ALL AND TO HIGHARDER.

[1]

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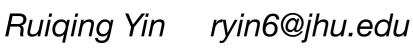






Motivation

- Surgeons have to manually operate the endoscope during the entire operation.
- The whole surgery can take up to one and a half hours.
- About 260,000 sinus cases performed in the US annually. [3]
- Endoscopic Sinus Surgery has been becoming the mainstay. [4]











Proposed Solution

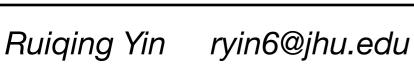
REMS by Galen Robotics

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Machine Learning

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Smart Endoscope + a happy Dr. Ishii :)



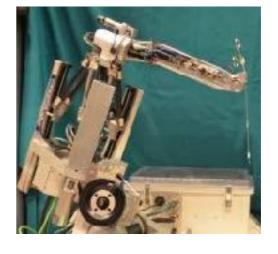


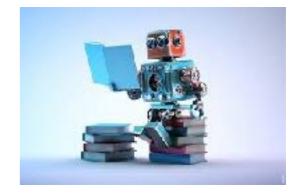












Project Scope

Robot Development

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- Experiment Design and Setup
- Experiment and Data Collecting
- Data Processing
- Machine Learning

- - -



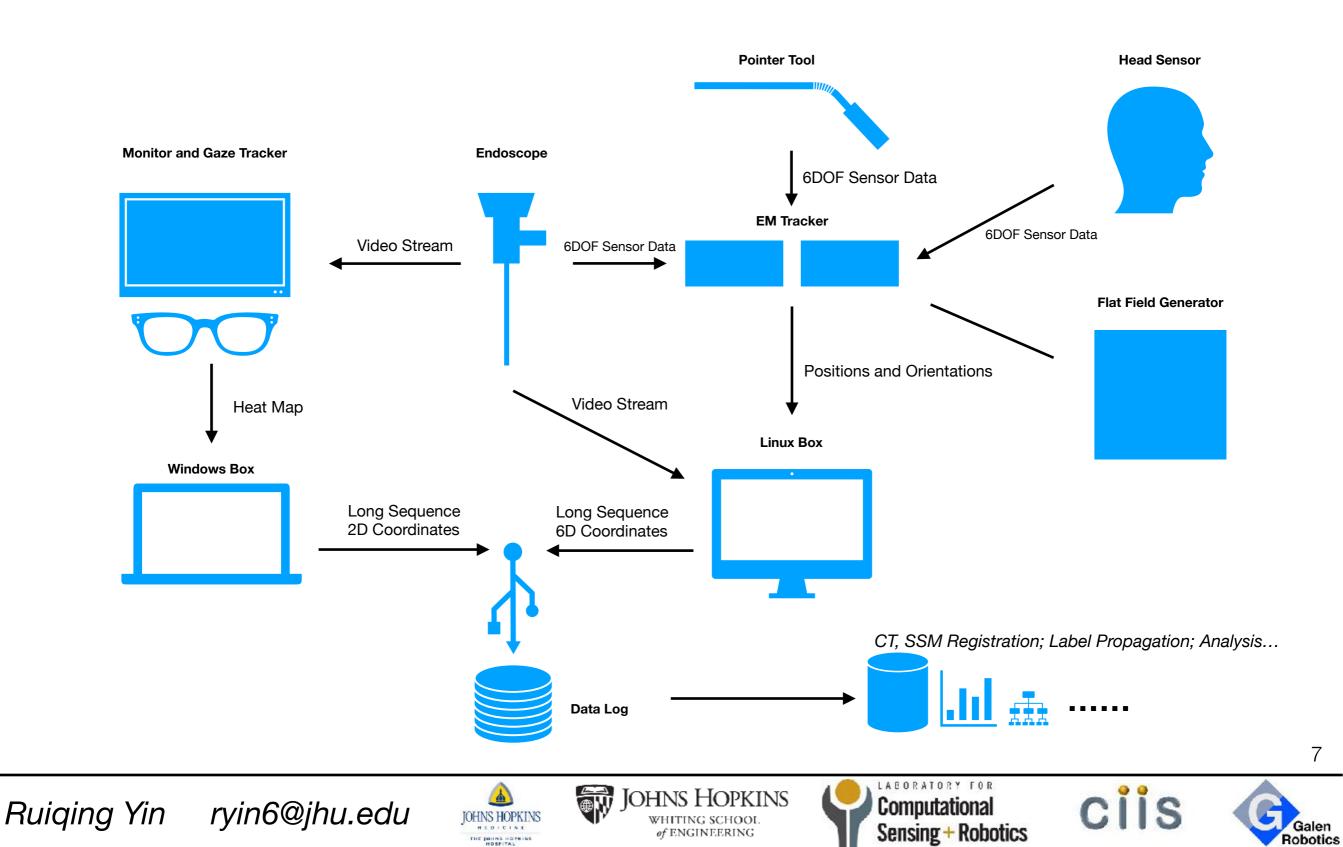






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Technical Approach



Technical Approach

- Tracking System Integration
 - Aurora EM Tracking System
 - 3 6DOF Sensors
 - Flat Field Generator
 - Gazepoint Gaze Tracker
- Tool Adapters Design
 - Pointer Tool
 - Endoscope Sensor Adapter
 - Head Sensor Adapter

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Technical Approach

- Data Logging System
 - Linux OS: Arurora Software/SDK, ROS
 - Windows OS: Gazepoint Software/SDK











Apparatus/BoM

1. Aurora System (Ordered)

- 1. Aurora 6DOF Reference, 25mm Disc x 2
- 2. Aurora 6DOF Cable Tool, 2.5 x 12mm
- 3. Aurora 6DOF Probe
- 4. Aurora Tabletop 50-70 Field Generator
- 5. Aurora V3 System Control Unit Kit
- 6. Aurora 4-port Sensor Interface Unit
- Gazepoint GP3 Eye Tracker (Ordered) 2.
- Monitor for Endoscope Video Streaming 3.
- Windows Workstation 4.
- Linux Workstation 5.
- **3D Printed Adapters** 6.



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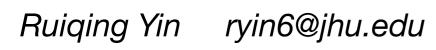
Sensing + Robotics





Deliverables

- **Minimum**: Hardware for a functional data collecting system.
- **Expected**: Hardware and software for a functional data collecting system.
- **Maximal**: Hardware and software for a functional data collecting system; data post processing program.











Dependencies

	Dependency	Solution	Alternative Plan	Status
1	Tracking Systems	Communicate with Dr. Taylor and Dr. Huang	Borrow similar equipment from Dr. Boctor	Solved
2	CAD Program	Download thru WSE Software Support	Student Design Lab/ CIIS Lab	Solved
3	3D Printers and Machine Shop	Contact WSE Manufacturing	Contact Outside Vendors	Solved
4	Familiarity with Surgery Process	Contact Dr. Ishii to shadow real cases	Read Papers about FESS	In Progress
5	Familiarity with Surgical Tools	Communicate with Dr. Inshii and Dr. Iordachita	Contact Dr. Razavi	In Progress
6	Experience with Tracking Systems	Communicate with Dr. Taylor and Dr. Boctor	Contact Equipment Manufactuers	Planned
7	Experience with ROS	Taking Robot System Programming with Dr. Whitcomb	Contact Paul Wilkening	In Progress
8	Gazepoint Software Able to Log	Communicate with Dr. Huang, Cong and Xingtong	Contact Gazepoint	Planned
9	Continuous Feedback from Mentors	Schedule a weekly meeting	Communication thru Emails	In Progress
10	Availability of Dr. Ishii	Schedule ahead with Dr. Ishii	No Alternative	Planned

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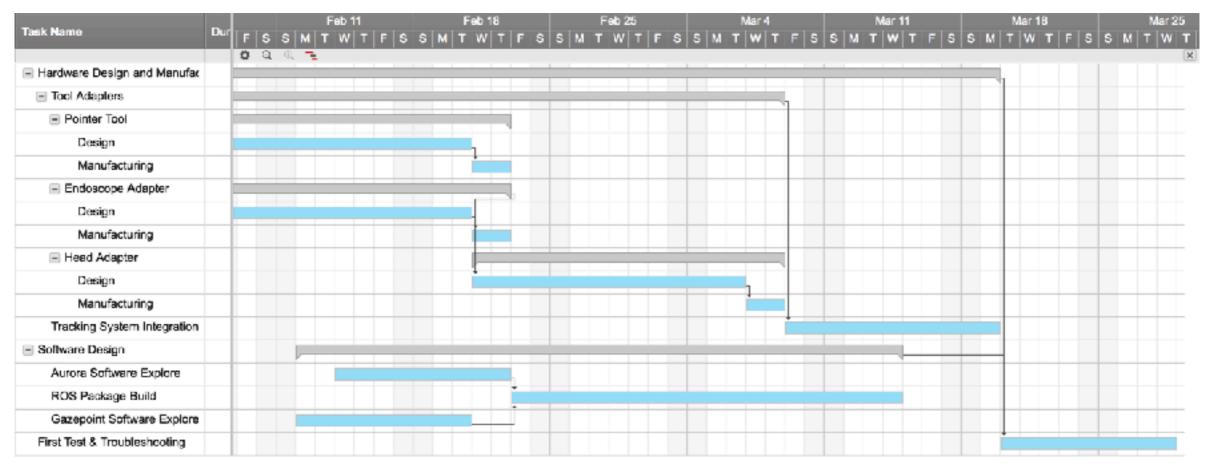
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Schedule



Milestones

- 1. Project Proposal
- 2. Tool Adapters Design Completion
- 3. Hardware Integration Completion
- 4. Software Development Completion
- 5. First Test and Troubleshooting

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Management Plan

- 1. Weekly meetings with mentors
- 2. Follow schedule and milestones

Reading List

- 1. Wormald, P. J. (2007). *Endoscopic sinus surgery* Thieme.
- 2. Amershi, S., Cakmak, M., Knox, W. B., & Kulesza, T. (2014). Power to the people: The role of humans in interactive machine learning. Al Magazine, 35(4), 105-120.
- 3. Akgun, B., Cakmak, M., Yoo, J. W., & Thomaz, A. L. (2012, March). Trajectories and keyframes for kinesthetic teaching: A human-robot interaction perspective. In Proceedings of the seventh annual ACM/IEEE international conference on Human-Robot Interaction (pp. 391-398). ACM.
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- 5. In Proceedings of the seventh annual ACM/IEEE international conference on Human-Robot Interaction (pp. 17-24). ACM.
- 6. Recording and playing back data: <u>http://wiki.ros.org/ROS/Tutorials/</u> <u>Recording%20and%20playing%20back%20data</u>



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- 1. MAYO FOUNDATION FOR MEDICAL EDUCATION AND RESEARCH. https:// www.mayoclinic.org/endoscopic-sinus-surgery/img-20007106
- 2. AMERICAN SINUS INSTITUTE. https://www.americansinus.com/types-ofsinus-surgeries/
- 3. Bhattacharyya, N. (2010). Ambulatory sinus and nasal surgery in the united states: Demographics and perioperative outcomes. The Laryngoscope, 120(3), 635-638.
- Venkatraman, G., Likosky, D. S., Zhou, W., Finlayson, S. R., & Goodman, D. C. (2010). Trends in endoscopic sinus surgery rates in the Medicare population. Archives of Otolaryngology–Head & Neck Surgery, 136(5), 426-430.











