







## **Deliverables Status Update**

Deliverables		Date	Status
Minimum	Experimental apparatus	03/15/2020	Met
	Documented code for surgical tool tracking software	03/25/2020	Met
Expected	Experimental data Documented code for tremor reduction assessment	04/07/2020	On schedule
	Documented code for tremor reduction assessment	04/07/2020	On schedule
	Report	04/30/2020	On schedule
Maximum	Academic paper	05/13/2020	On schedule

path         filename         pig cadaver (v/x)         left (R/FH)         color           /Users/suemincho/Research/Laryngeal_Tremor_Analysis/Spring2020/CIS2/Microscope_Videos         DeepaTest01A.mov         x         FH         green           /Users/suemincho/Research/Laryngeal_Tremor_Analysis/Spring2020/CIS2/Microscope_Videos         DeepaTest01B.mov         x         FH         blue           /Users/suemincho/Research/Laryngeal_Tremor_Analysis/Spring2020/CIS2/Microscope_Videos         DeepaTest02.mov         x         FH         blue           /Users/suemincho/Research/Laryngeal_Tremor_Analysis/Spring2020/CIS2/Microscope_Videos         DeepaTest02.mov         x         FH         blue           /Users/suemincho/Research/Laryngeal_Tremor_Analysis/Spring2020/CIS2/Microscope_Videos         DeepaTest03.mov         x         FH         purple	right (R/FH) FH FH R R	color length blue purple green	th (s) 62 19
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/Users/suemincho/Research/Laryngeal_Tremor_Analysis/Spring2020/CIS2/Microscope_Videos Microscope_B_1.mov x FH purple	FH	green	35
<sup>1</sup> /Users/suemincho/Research/Laryngeal_Tremor_Analysis/Spring2020/CIS2/Microscope_Videos Microscope_B_2.mov x FH blue	FH	green	21
/Users/suemincho/Research/Laryngeal_Tremor_Analysis/Spring2020/CIS2/Microscope_Videos Microscope_B_3.mov x FH purple	FH	blue	12
/Users/suemincho/Research/Laryngeal_Tremor_Analysis/Spring2020/CIS2/Microscope_Videos Microscope_B_4.mov x FH green	FH	blue	7
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Tracking Algorithm	CSRT (Discriminative Correlation Filter (with Channel and Spatial Reliability))	KCF (Kernelized Correlation Filters)	BOOSTING	MIL (Multiple Instance Learning)	TLD (Tracking, learning and detection)	MEDIANFLOW	MOSSE (Minimum Output Sum of Squared Error)
Pros	- higher object tracking accuracy	- Decent accuracy and speed	none	- better than BOOSTING - reasonable job under partial occlusion	- works the best under occlusion over multiple frames - tracks best over scale changes	excellent tracking failure reporting - works well when motion is predictable and there is no occlusion	- very very fast
Cons	- slower fps throughput	- does not recover from full occlusion	- mediocre tracking performance - does not reliably know when tracking has failed	- does not report tracking failure reliably - does not recover from full occlusion	- too many false positives	- fails under large motion	<ul> <li>not as accurate</li> <li>Reports failures well</li> <li>model fails when then is too large of a jump in motion</li> </ul>
Performance in Microscope Video	Best	Tracking fails for more than half of video	Not too bad	Slow and inaccurate	Very slow and very inaccurate	Only good when there is no light change or fast movement	Fast but loses tracking for about half of video







## Problem

→ For some colors (e.g. blue), tracker shows evident tremor without actual tremor present

Possible Solutions

- Perform image pre-processing to increase contrast between colored instrument foreground and background
- Compute local optical flow within a window and find frame-to-frame correlation



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## **Dependency Status**

Dependency	Proposed Solution	Alternative Plan	Effect on Milestone/Deliverable	Needed By (Status)
Access to Computer	Use personal laptop and back up on external	A) Use spare personal laptop	Needed for entire project	Immediately (Resolved)
	hard drive			
Access to OpenCV	Use OpenCV that is already installed on my	A) Use different opensource computer	Needed for surgical tool tracking software	Immediately (Resolved)
	computer	vision packages/libraries		
Video acquisition software	Coordinate with Balazs and Prof. Taylor to	A) Use existing data	Needed for microscope video acquisition	03/16/2020 (Resolved)
(e.g. frame grabber)	acquire necessary software			
Second camera for stereo and adapter	Buy camera and adapter from Haag-Streit	A) Use IR camera for 2 <sup>nd</sup> view (need cable	Needed for stereo image processing	03/16/2020 (Resolved)
→ Use in follow-up study	(Coordinate with Dr. Taylor)	& acquisition software)		
		B) Do analysis using monocular stereo		
Experimental protocol	Coordinate with Prof. Taylor	A) Use existing data	Needed for user study	03/16/2020 (Resolved)
Equipment (laryngeal tools, pig larynxes,	Coordinate with Dr. Taylor and surgeons, and	A) Modify user study schedule accordingly	Needed for user study	03/16/2020 (Resolved)
laryngoscopes, microscope, camera, Galen	order/gain access in advance			
robot)				
Data - videos	Contact surgeons regularly	A) Use old data	Needed as a new dataset to analyze for	03/27/2020 (Resolved)
			this project	
Availability of surgeons	Work through loan and Deepa	A) Use old data	Needed for user study	03/16/2020 (Resolved)
→ Schedule user study with more surgeons in follow-up study		B) Enlist graduate students		
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Schedule a	nd Wanage	ement Plan		Work-in-progress     Estimated Duration
	February	March	April	May
		Complete Develop	tion of Software ment/Adaptation + Documentation	Modify software
Step 1 Develop/adapt + document surgical tool tracking software	100%	Feb 10 – Mar 25	Completion of User Stu and Data Collection Apr 10. → Mor 18	dy
Step 2 Conduct user study		<b>100%</b> Mar 10	6 – Apr 10 Oat	npletion of a Analysis 19
Step 3 Develop tremor reduction assessment pipeline + analyze data		59	6 Mar 27 – Apr 19	Completion of Report
Step 4 Write report			Apr 13 – Apr 30	Completion of Academic Paper May 13
Step 5 Write academic paper				Apr 27 – May 13
<b><u>Management Plan</u></b> ) Weekly meetings (Galen r ) Meetings with Balazs as n ) Additional meetings as ne	neeting with Professor leeded eeded	r Taylor and surgeons)		

